

Monte Carlo

Variance Reduction

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Variance Reduction

Introduction

- Main techniques:
 - Antithetic Sampling
 - Stratification
 - Russian Roulette
 - Importance Sampling
 - Metropolis Sampling

Antithetic Sampling

Antithetic Sampling

Main Idea

- Monte-Carlo leads to error cancellation; and this is our aim when we do antithetic sampling; i.e., we are trying to balance samples with their opposites.
- We look for a value of $f(\mathbf{x})$ that gives us an opposite value \mathbf{x}^\star ; one time low and the other high.
- How?
 - If the $p(\mathbf{x})$ is symmetric (e.g., the uniform), we can generate \mathbf{x}^\star as:

$$\mathbf{x}^\star = 2\mathbf{c} - \mathbf{x},$$

where \mathbf{c} is the center point of the domain.

Antithetic Sampling

Main Idea

- The estimate, for averages, changes into:

$$\hat{\mu}_n^\star = \frac{1}{n} \sum_{i=1}^{\frac{n}{2}} \left(f(\mathbf{x}_i) + f(\mathbf{x}_i^\star) \right),$$

where n is even.

- The variance here is defined as:

$$\text{Var}(\hat{\mu}_n^\star) = \text{Var}\left(\frac{1}{n} \sum_{i=1}^{\frac{n}{2}} f(\mathbf{x}_i) + f(\mathbf{x}_i^\star)\right) = \frac{\sigma^2}{n} (1 + \rho) \quad \rho \in [-1, 1].$$

- ρ is the correlation between $f(\mathbf{x})$ and $f(\mathbf{x}^\star)$. Note that in the best case, $\rho = -1$, we have the exact answer, otherwise in the worst case, $\rho = 1$, we doubled the variance!

Antithetic Sampling

Example: Integration

- Let's integrate

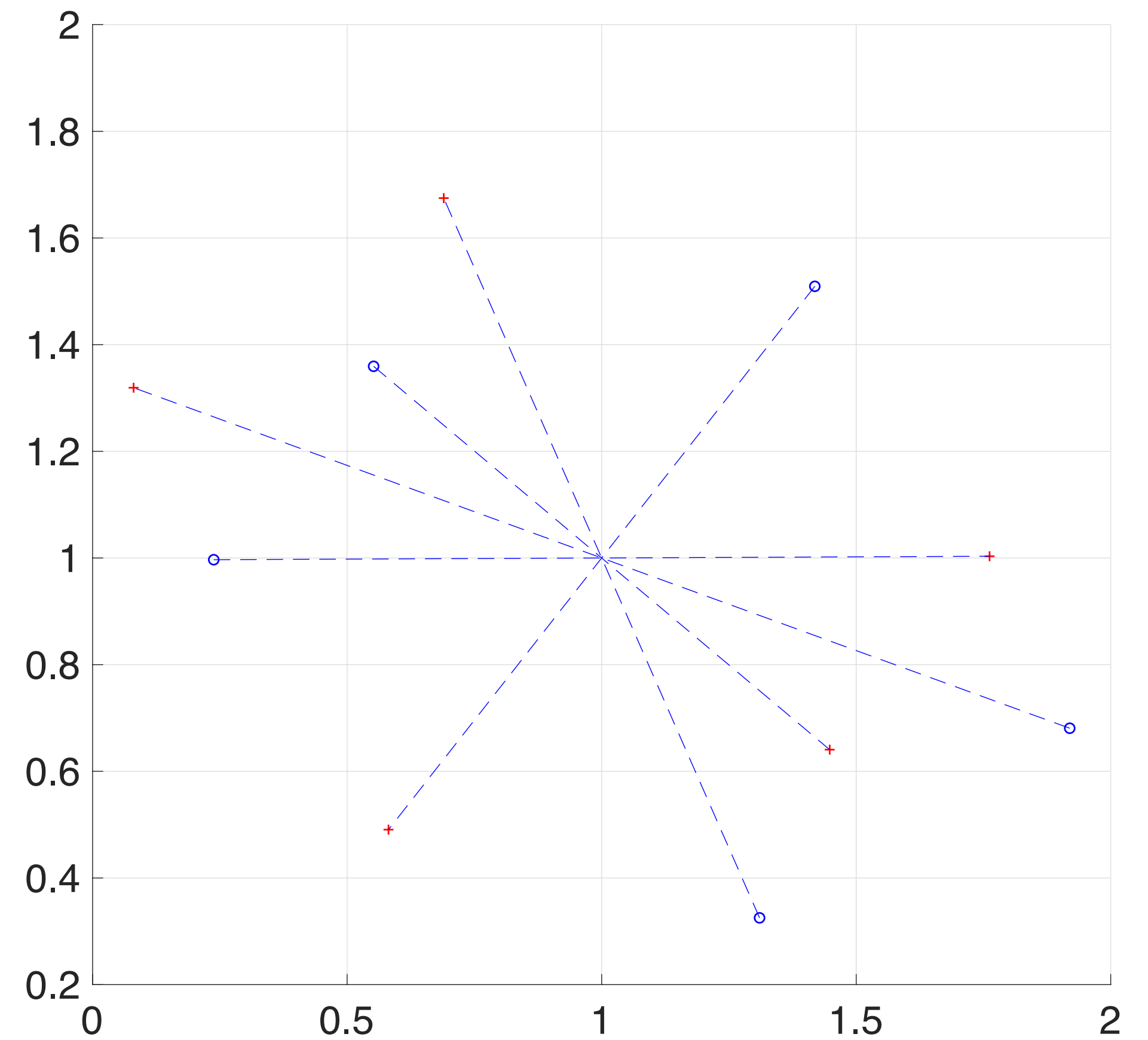
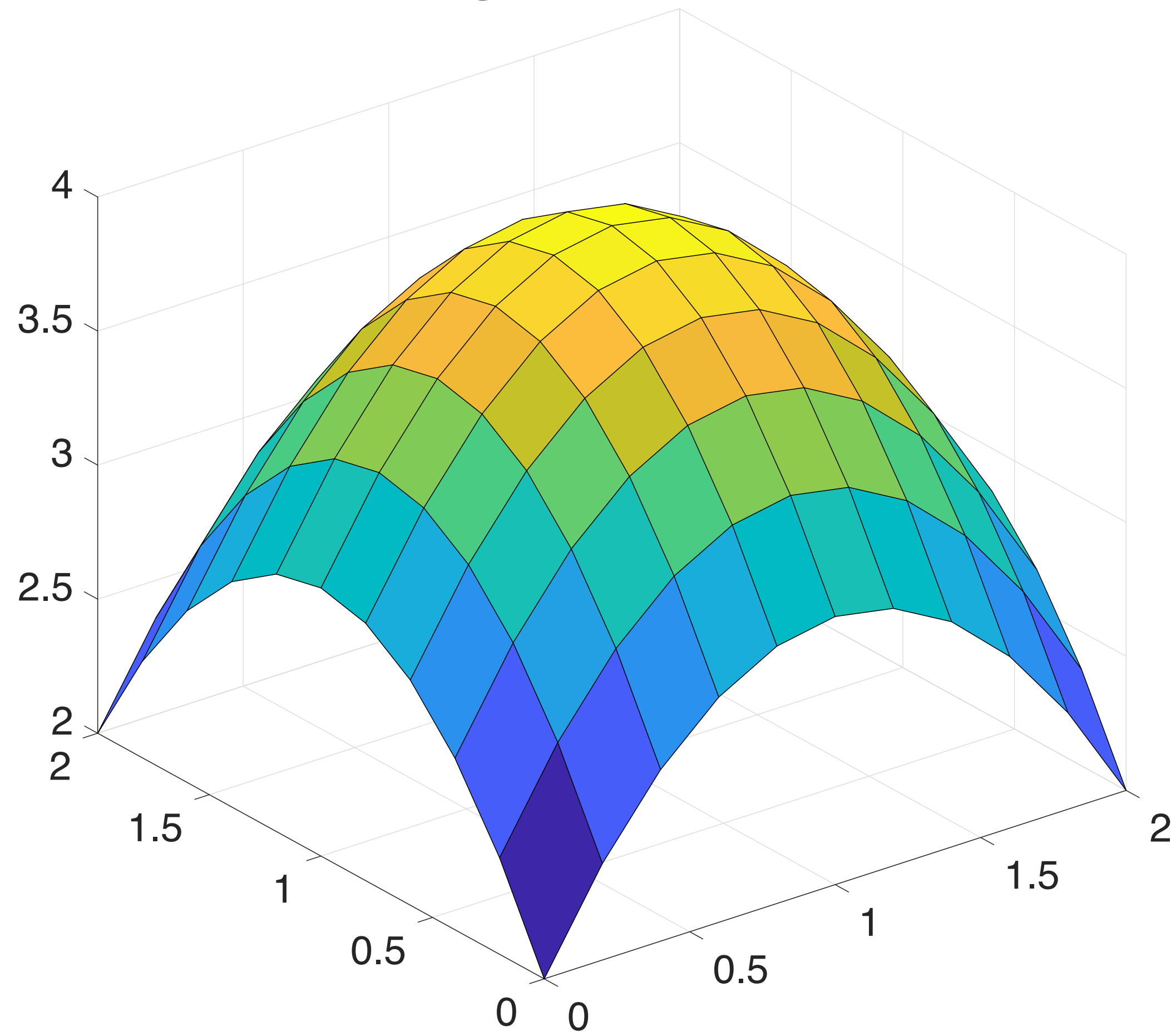
$$f(\mathbf{X}) = -((x_1 - c_1)^2 + (x_2 - c_2)^2) + 4 \quad \mathbf{x} \in [0,2]^2, \quad \mathbf{c} = (1,1).$$

- We create antithetic samples as:

$$\mathbf{x}_i^\star = 2\mathbf{c} - \mathbf{x}_i = (2,2) - \mathbf{x}_i$$

Antithetic Sampling

Example: Integration



Antithetic Sampling

Example: Stocks

- Let's assume we have a return of a portfolio, \mathbf{X} , with n stocks with investment proportional to $\alpha_i \geq 0$ (they are normalized):

$$f(\mathbf{X}) = \log \left(\sum_{i=1}^n \alpha_i \exp(X_i) \right).$$

- Let's assume that equally invested in each stock; i.e., $\alpha_i = n^{-1}$, and $X_i \sim N(\mu = 0.001, \sigma = 0.03)$. We create antithetic samples as:

$$X_i^* = 2\mu - X_i = 0.002 - X_i$$

Stratification

Stratification

Main Idea

- This strategy is the follow:
 - To split the domain of X into different regions.
 - To sample points in each region
 - To combine the results of each region; e.g., to estimate $\mathbb{E}(f(X))$.
- If each region get an equal number of samples, we should improve the quality of our estimate.

Stratification

Main Idea

- So our goal is to compute:

$$\mathbb{E}(f(\mathbf{X})) = \int_{\Omega} f(\mathbf{x})p(\mathbf{x})d\mathbf{x}.$$

- We partition Ω into K regions, $\Omega_1, \dots, \Omega_K$, where:

$$\omega_j = P(\mathbf{X} \in \Omega_j) \text{ where } p_j(\mathbf{x}) = \omega_j^{-1}p(\mathbf{x})1_{\mathbf{x} \in \Omega_j}$$

- For the j -th region, we generate n_j samples, $\mathbf{X}_{j,1}, \dots, \mathbf{X}_{j,n_j}$, according to $p_j(\mathbf{x})$.

$$\hat{\mu} = \sum_{j=1}^K \frac{\omega_j}{n_j} \sum_{i=1}^{n_j} f(\mathbf{X}_{i,j}).$$

Stratification

Main Idea

- This sampling is unbiased:

$$\begin{aligned}\mathbb{E}(\hat{\mu}) &= \sum_{j=1}^K \omega_j \mathbb{E} \left(\frac{1}{n_j} \sum_{i=1}^{n_j} f(\mathbf{X}_{j,i}) \right) = \sum_{j=1}^K \omega_j \int_{\Omega_j} f(\mathbf{x}) p_j(\mathbf{x}) d\mathbf{x} \\ &= \sum_{j=1}^K \int_{\Omega_j} f(\mathbf{x}) p(\mathbf{x}) d\mathbf{x} = \int_{\Omega} f(\mathbf{x}) p(\mathbf{x}) d\mathbf{x} = \mu\end{aligned}$$

Stratification

Main Idea

- A typical allocation for n_j is proportional to ω_j :

$$n_j = \lceil n\omega_j \rceil.$$

- This leads to:

$$\hat{\mu} = \frac{1}{n} \sum_{j=1}^K \sum_{i=1}^{n_j} f(\mathbf{X}_{i,j}).$$

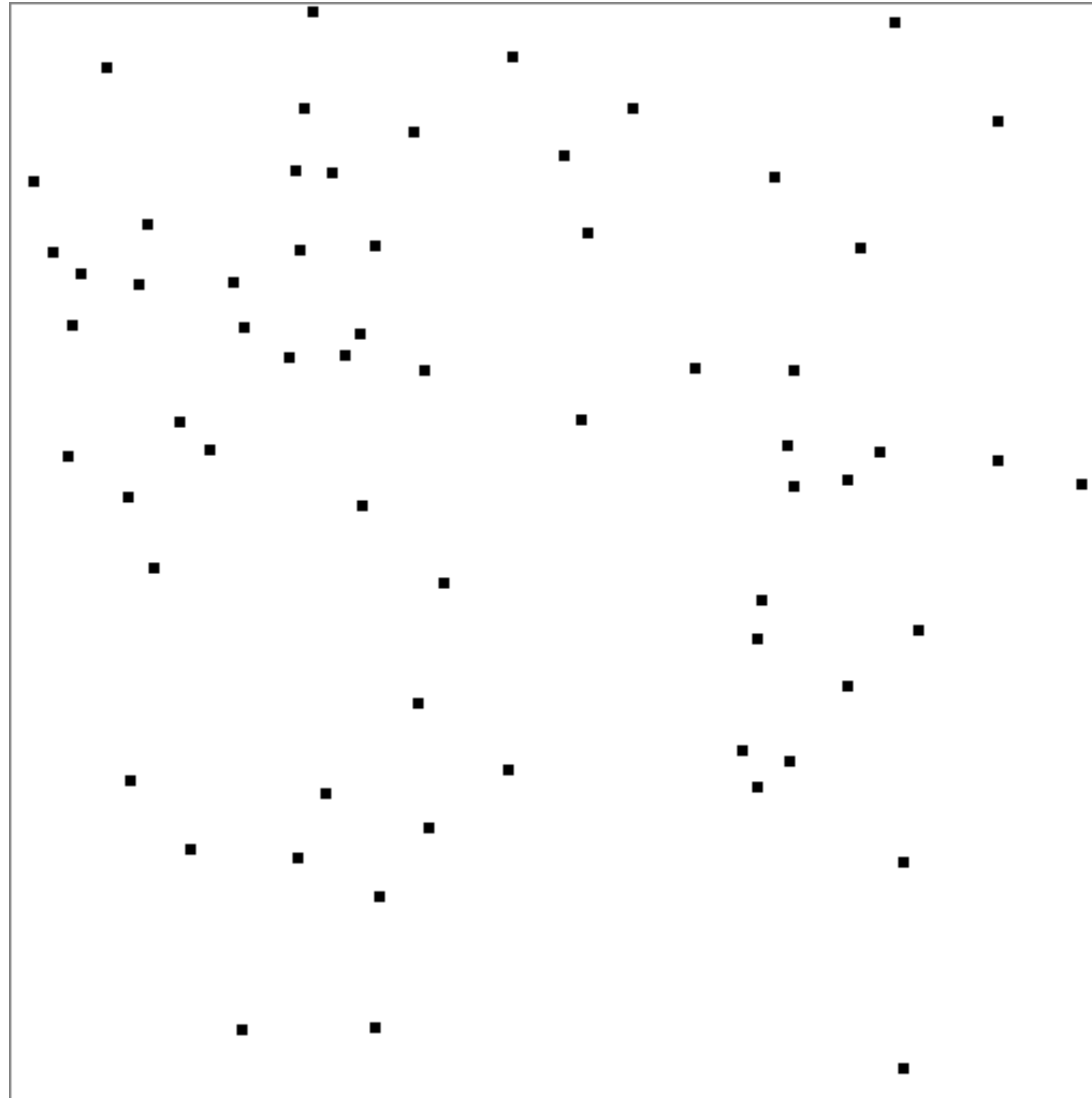
- Note that:

$$\hat{\mu}_j = \frac{1}{n_j} \sum_{i=1}^{n_j} Y_{i,j} \quad s_j^2 = \frac{1}{n_j - 1} \sum_{i=1}^{n_j} (Y_{i,j} - \hat{\mu}_j)^2 \quad \hat{\text{var}}(\hat{\mu}) = \sum_{j=1}^K \omega_j^2 \frac{s_j^2}{n_j}.$$

- This means that: $\hat{\mu} \pm 2.58\sqrt{\hat{\text{var}}(\hat{\mu})}$.

Stratification

Example



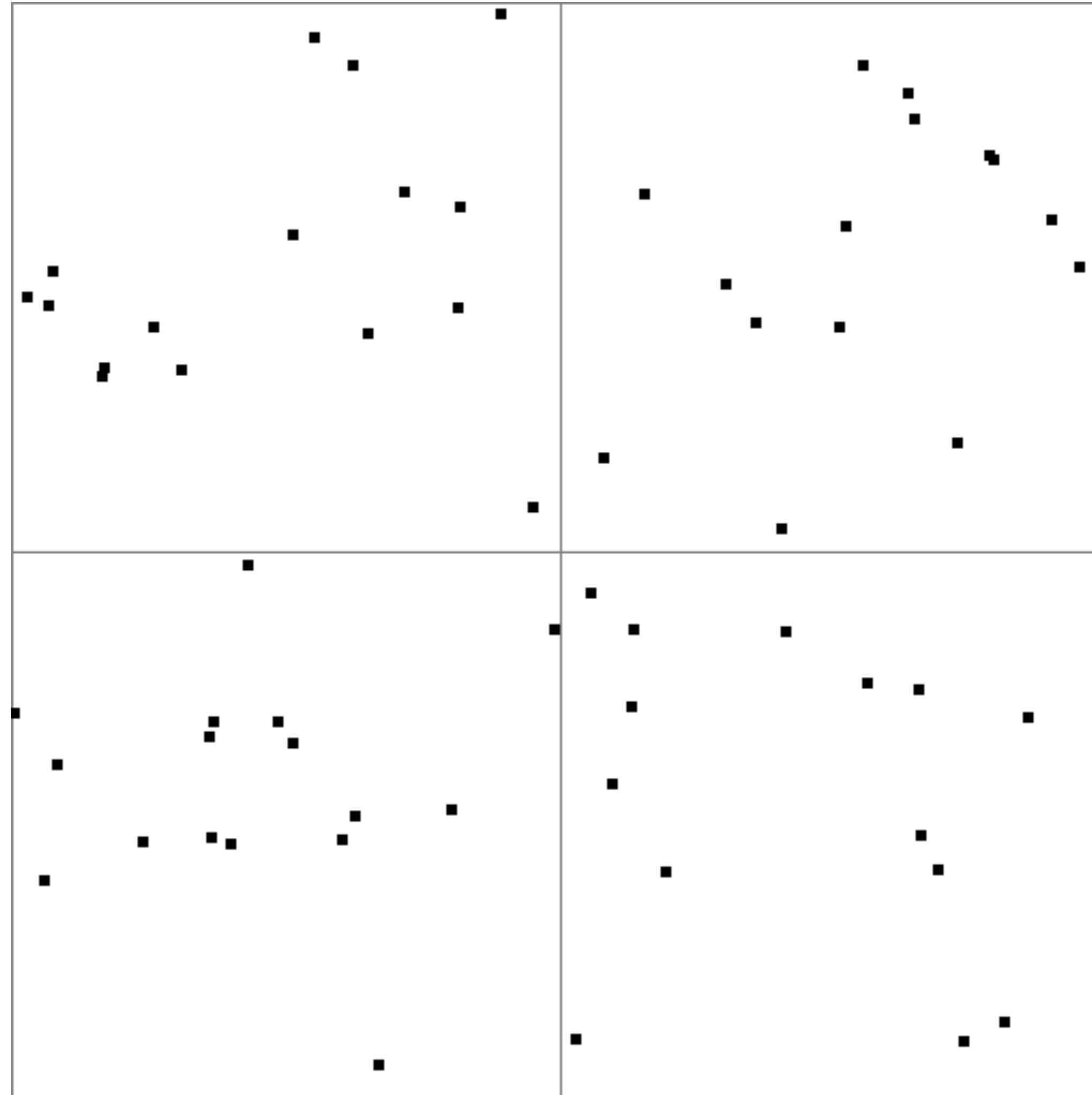
$$n = 64$$

$$s = 1$$

$$n_s = 64$$

Stratification

Example



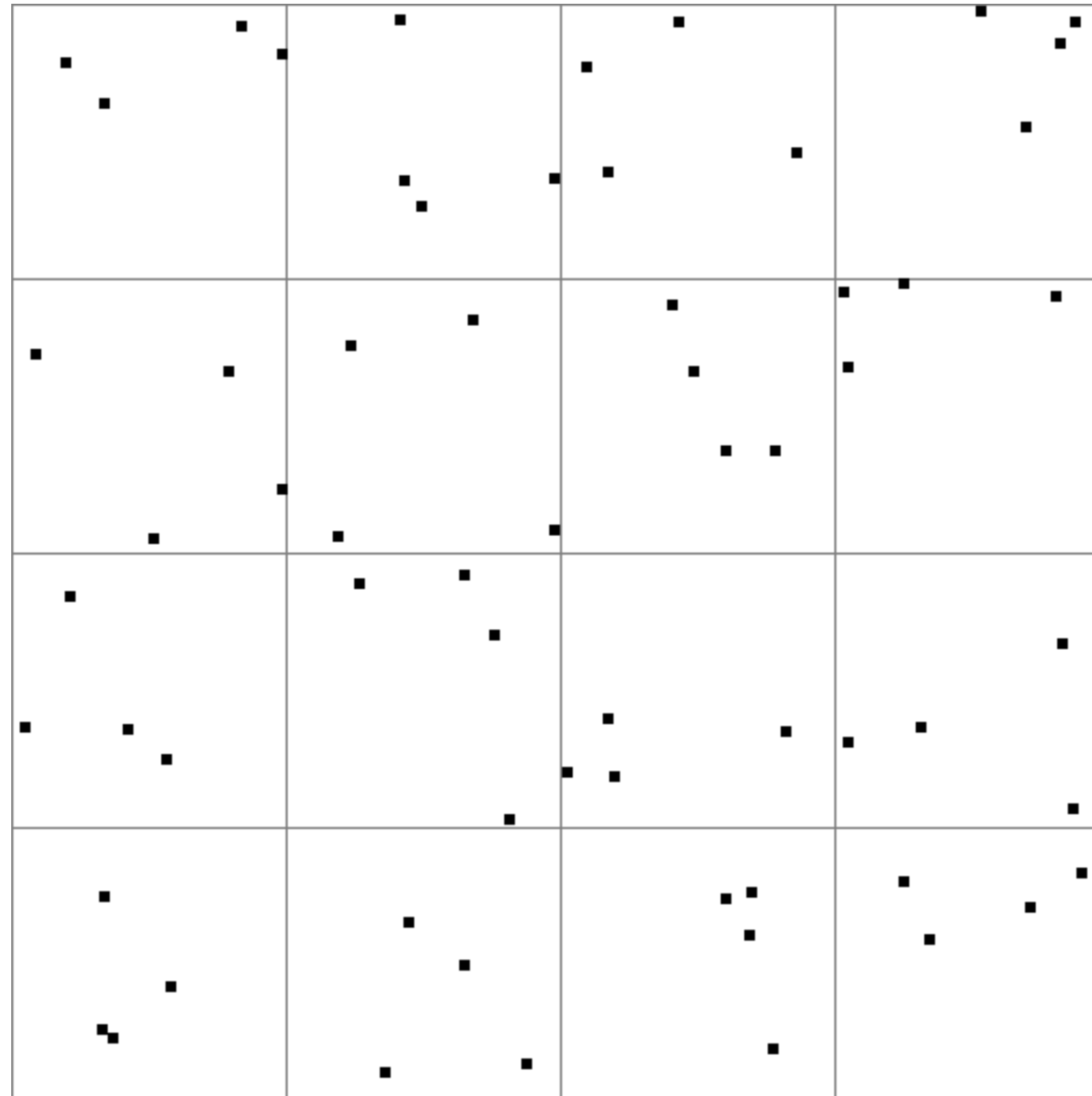
$$n = 64$$

$$s = 4$$

$$n_s = 16$$

Stratification

Example



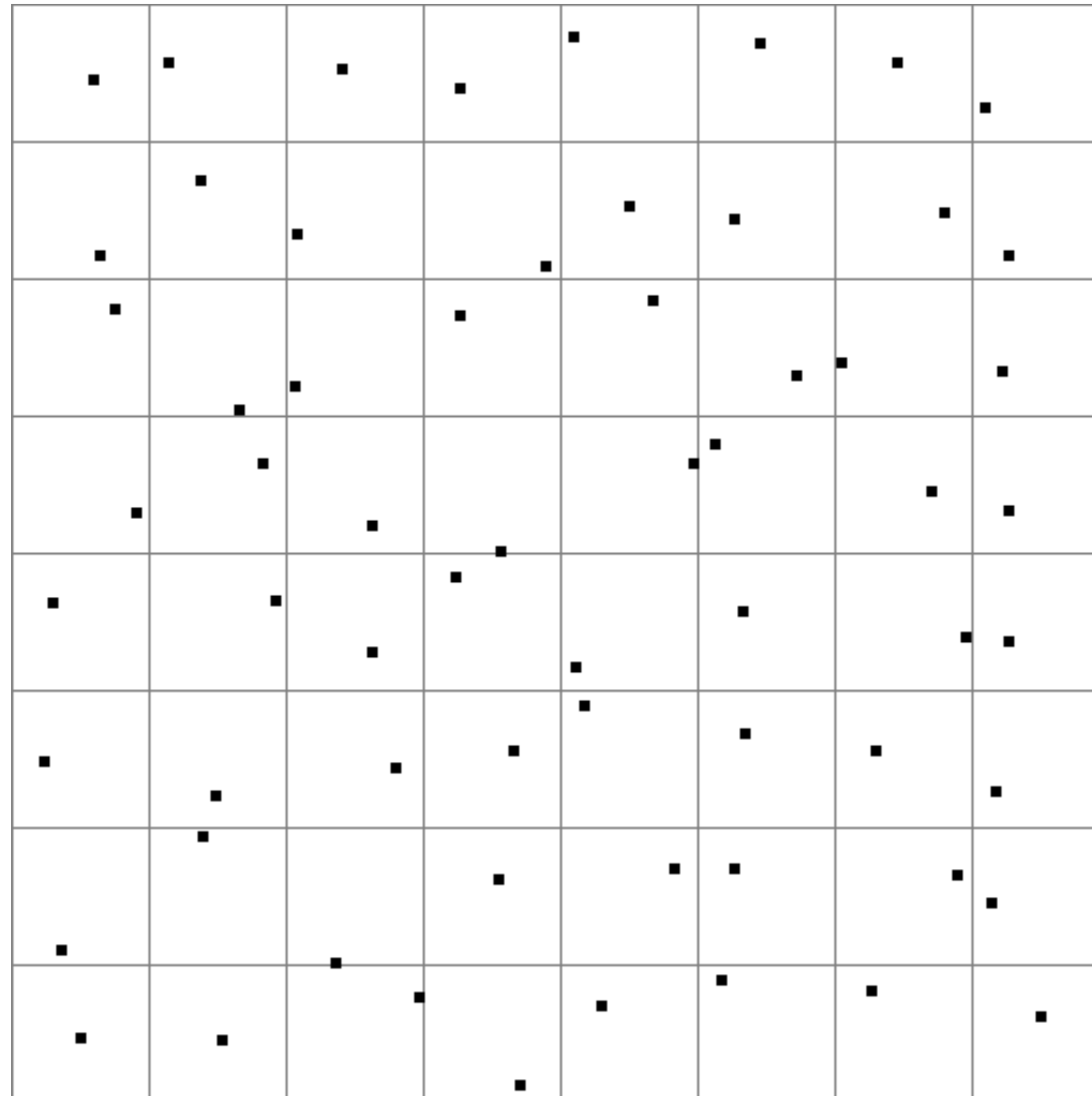
$$n = 64$$

$$s = 16$$

$$n_s = 4$$

Stratification

Example



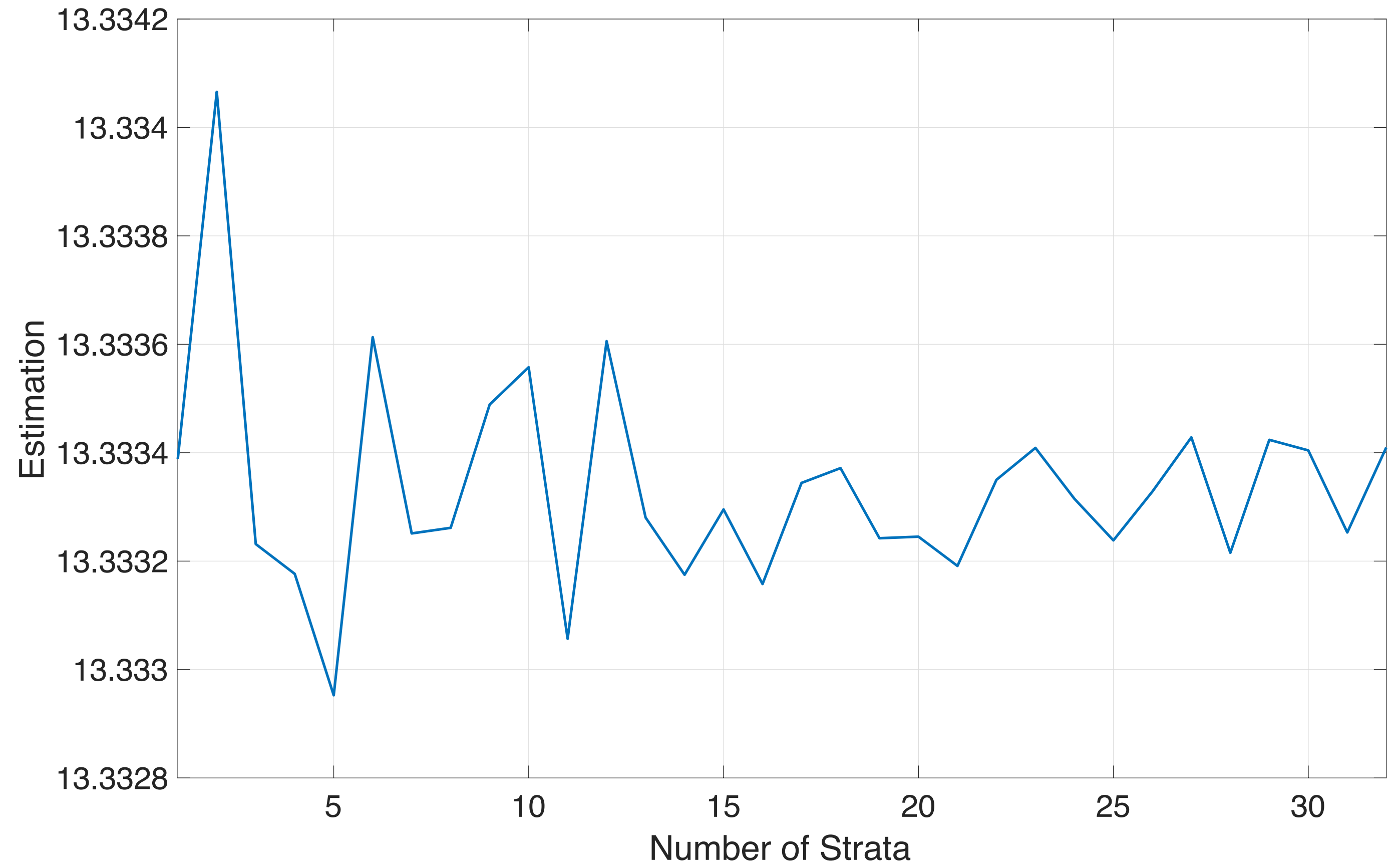
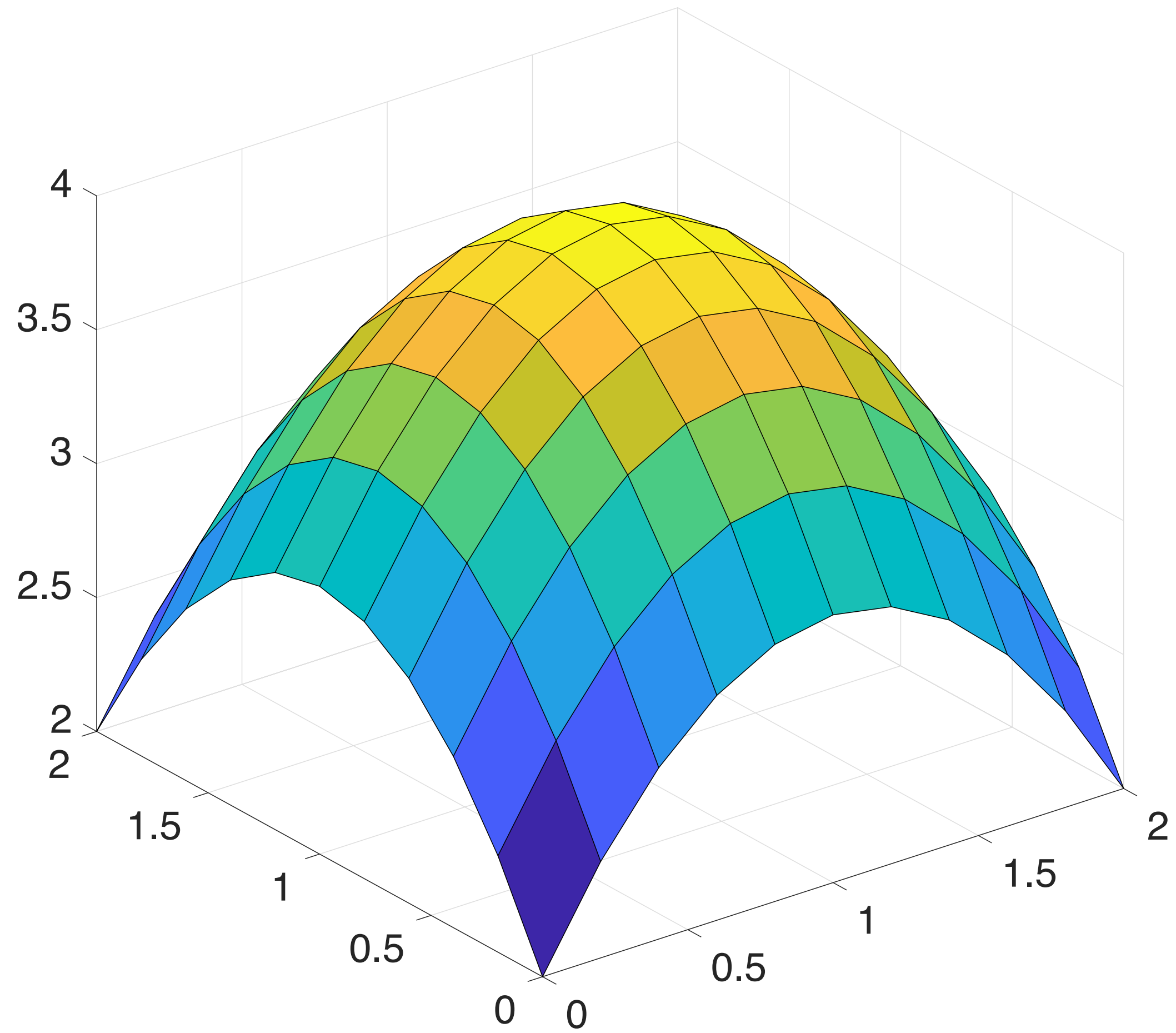
$$n = 64$$

$$s = 64$$

$$n_s = 1$$

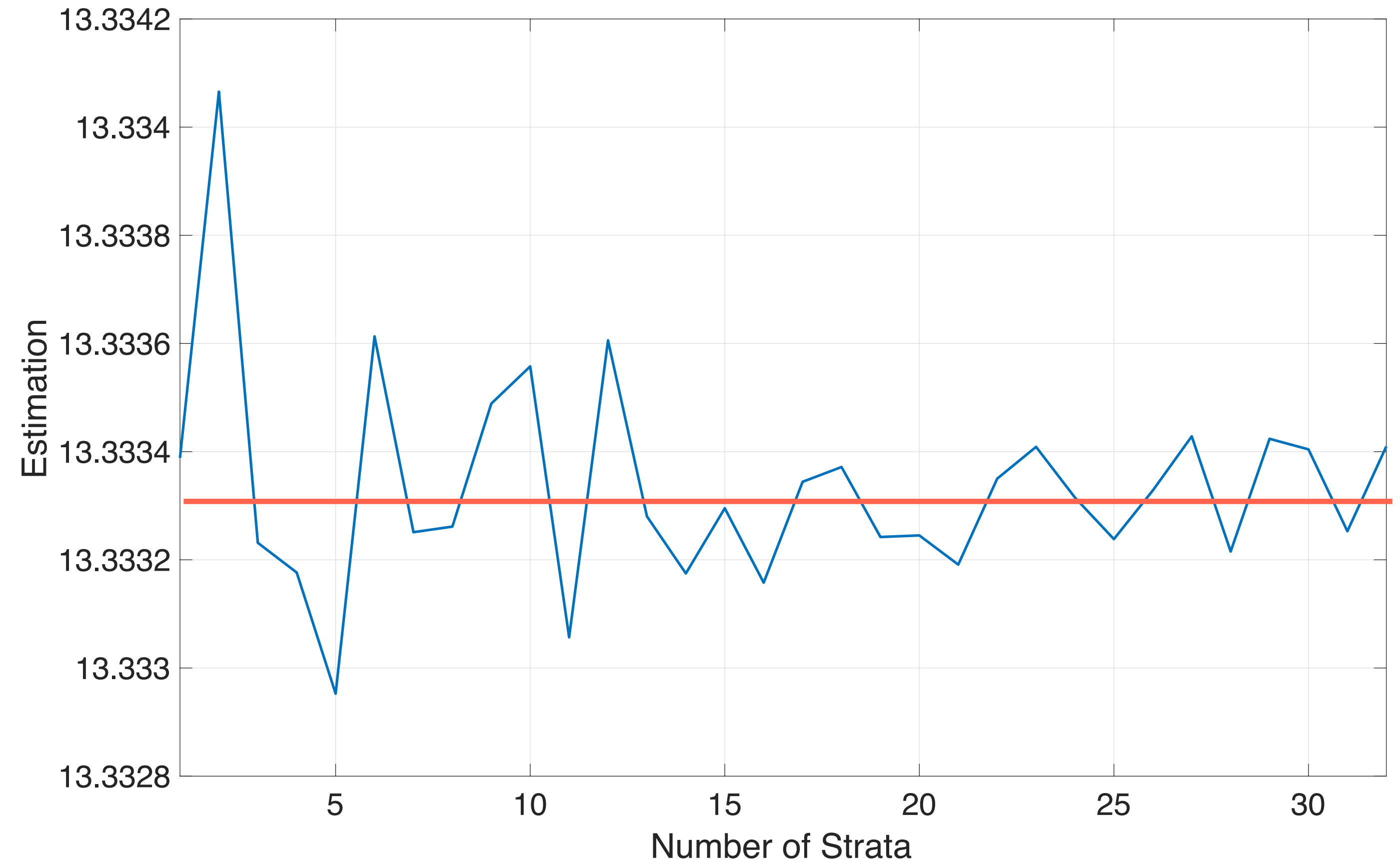
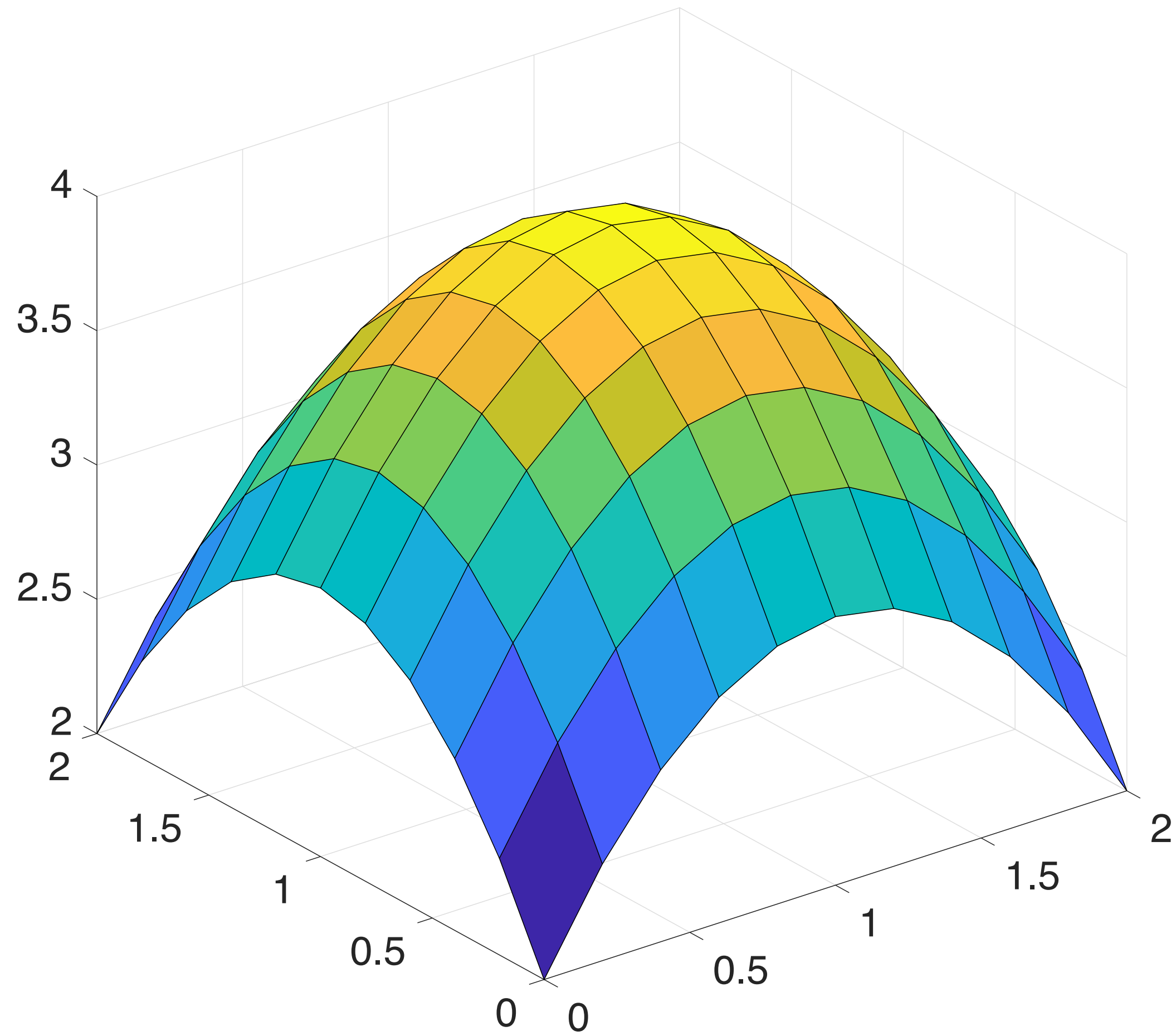
Stratification

Example



Stratification

Example



n-Rooks Sampling

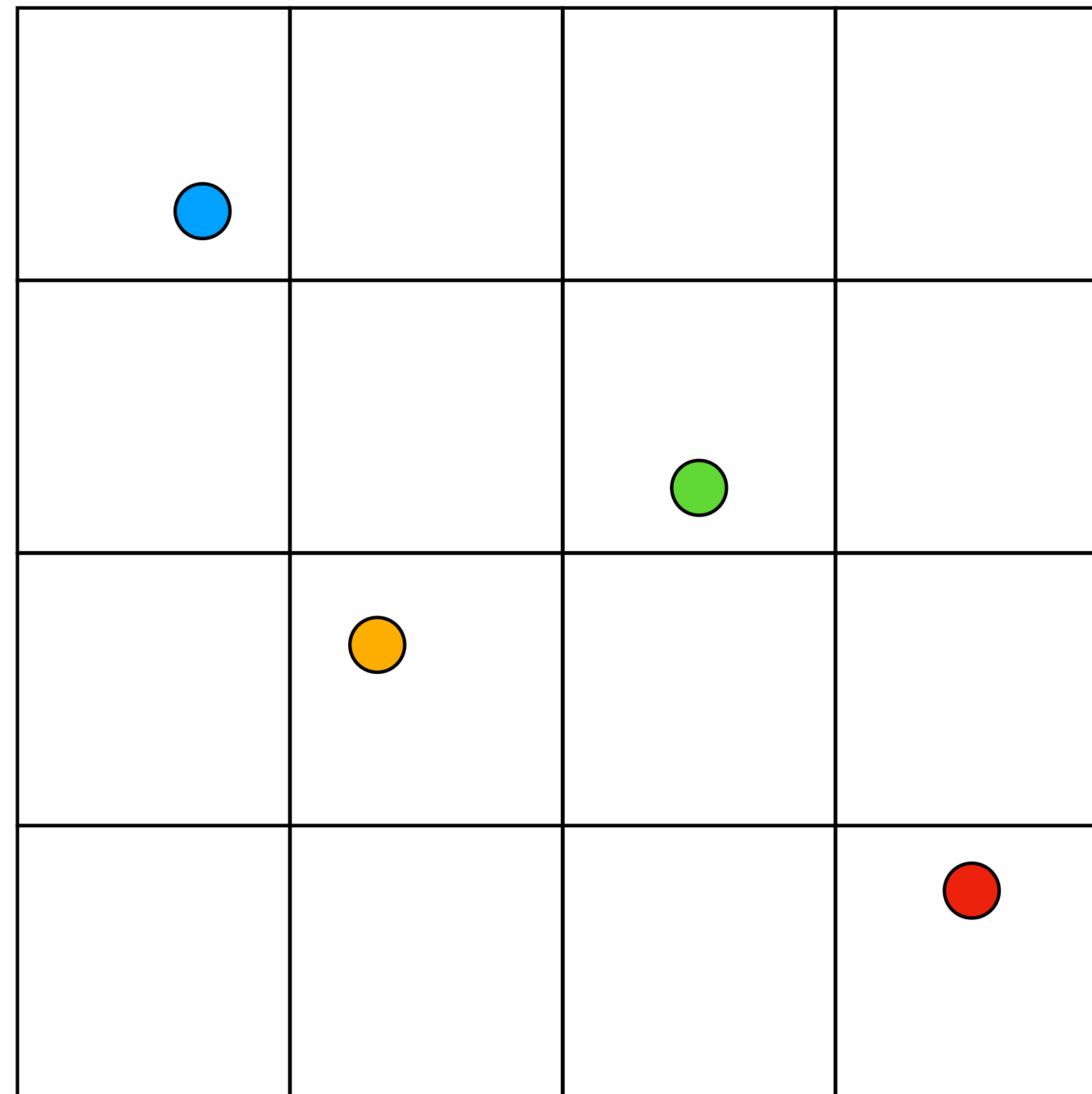
n -Rooks Sampling

Main Idea

- Stratification has an issue; the curse of dimensionality:
 - If we divide our domain with sub-cubes with side $1/m$ and we place just a sample per cube, we need $n = m^d$ samples.
 - This becomes a very large numbers when we start to have many dimensions in our problem!
 - This is a similar problem that we have when dealing with regular grids.
 - A solution is to draw a sample for each dimension component for $\mathbf{X} \sim \mathbf{U}(0,1)^d$.

n -Rooks Sampling

Main Idea



n -Rooks Sampling

Main Idea

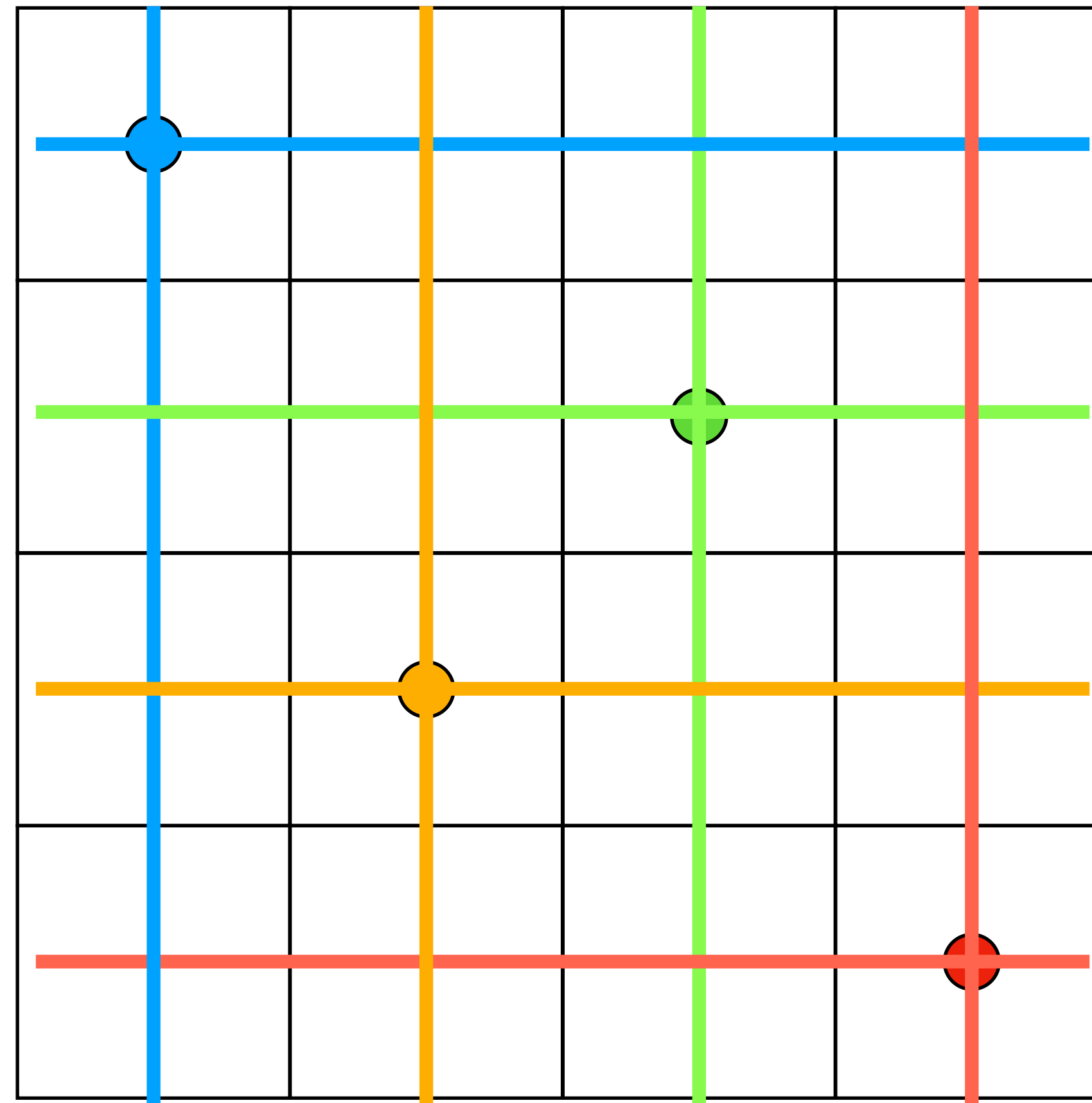
- How do we generate samples?

$$X_{i,j} = \frac{1}{n} \left(\pi_j(i-1) + U_{i,j} \right) \quad i \in [1,n], j \in [1,d]$$

- Where π_j is a uniform random permutations of the set $\{0, \dots, n-1\}$ and $U_{i,j} \sim \mathbf{U}[0,1)$.
- The name comes from a chess analogy: we place a sample as it were a rook controlling the rows and columns where it is placed on the chess board.
 - This method has been discovered several times in different fields and it has different names: Latin Hypercube Sampling, Lattice Sampling, etc.

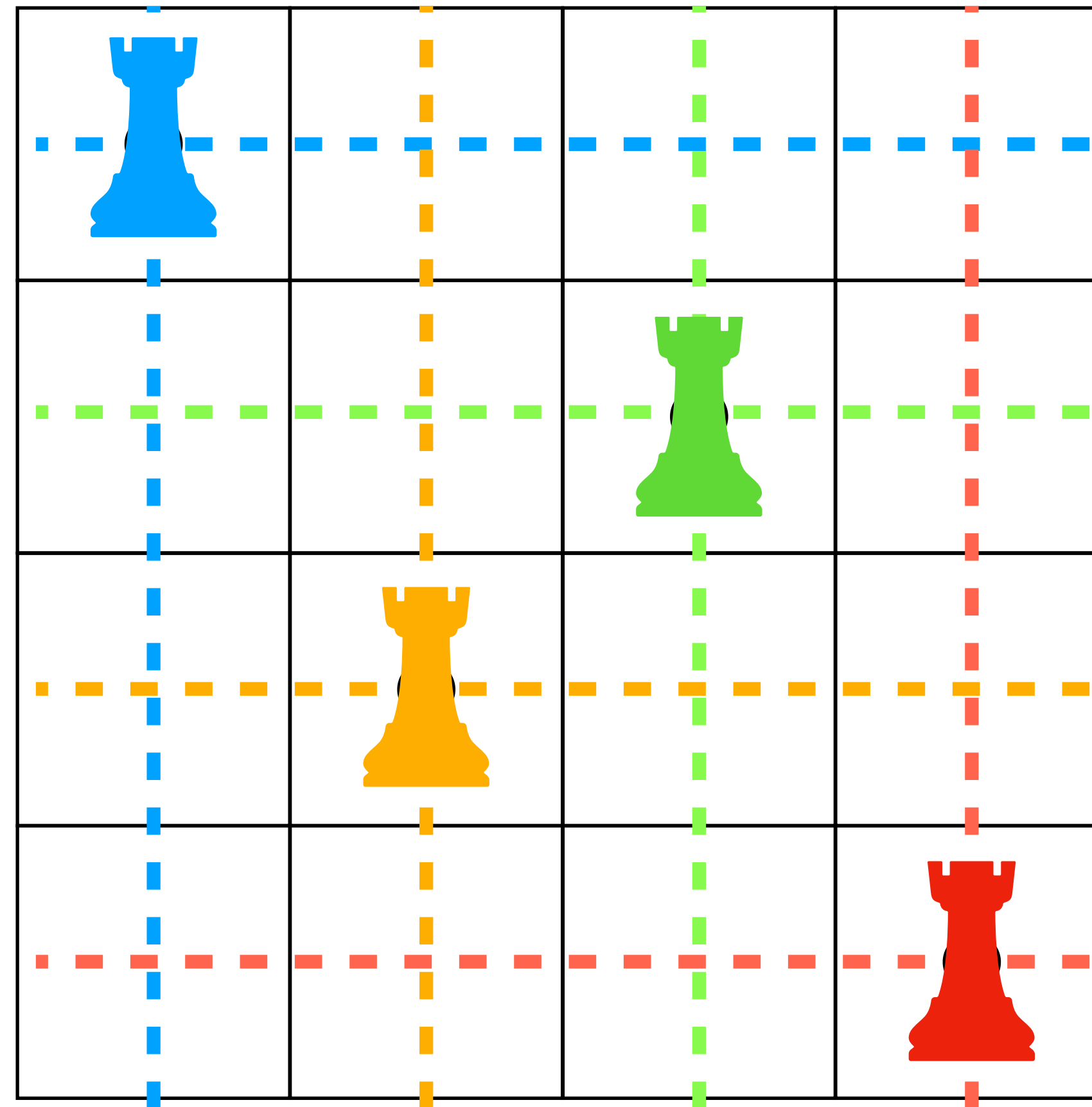
n -Rooks Sampling

Main Idea



n -Rooks Sampling

Main Idea



n -Rooks Sampling

Main Idea

- This sampling works best when we have additive functions:

$$f_a(\mathbf{x}) = f_0 + \sum_{i=1}^d f_i(x_i).$$

- This means that its variance is:

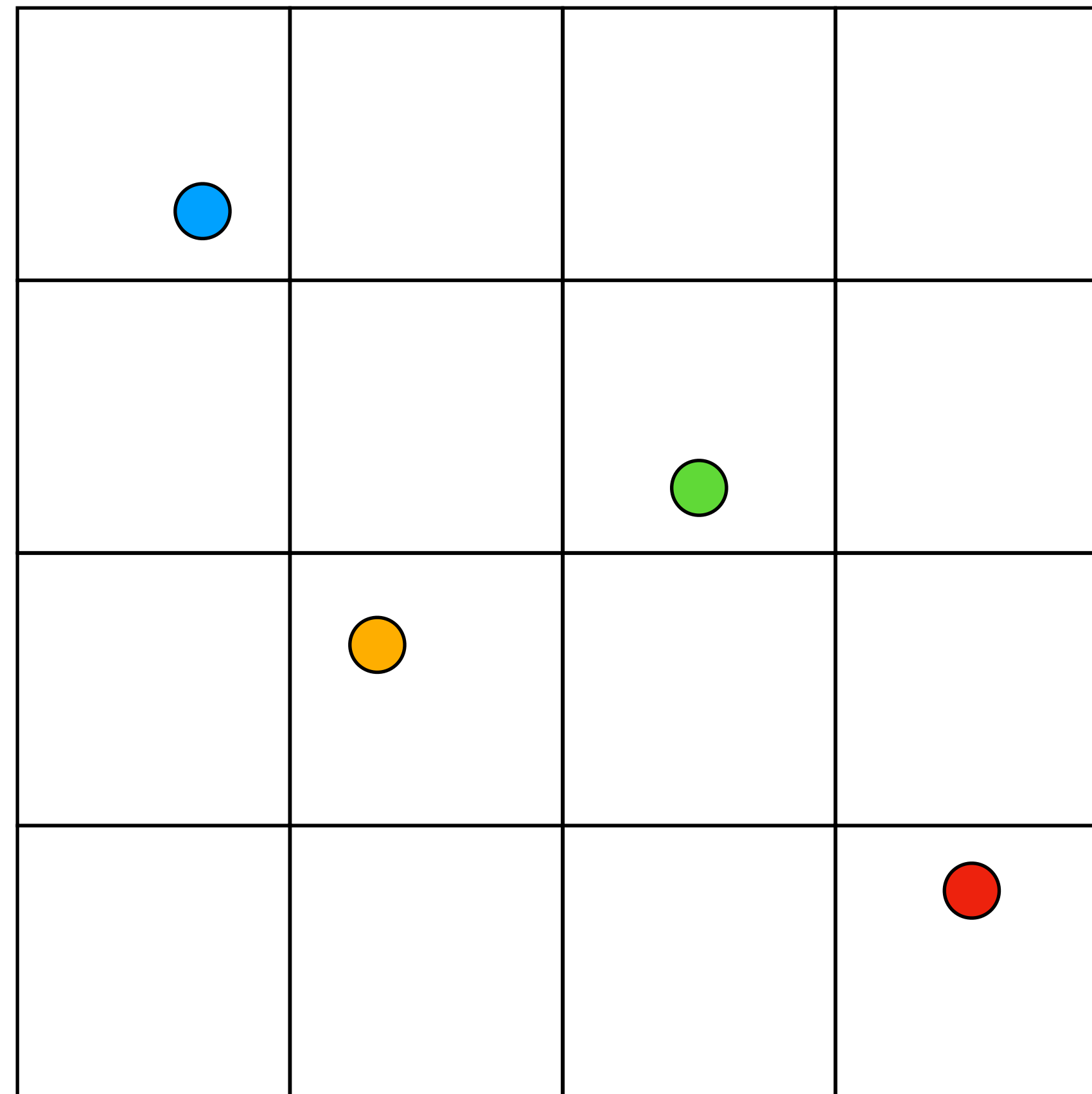
$$\text{Var}(\hat{\mu}) = \frac{1}{n} \int r(\mathbf{x})^2 d\mathbf{x} \leq \frac{\sigma^2}{n-1} + o\left(\frac{1}{n}\right) \quad r(\mathbf{x}) = f(\mathbf{x}) - f_a(\mathbf{x}).$$

- In the worst case, this sampling increases the variance by:

$$\frac{n}{n-1}.$$

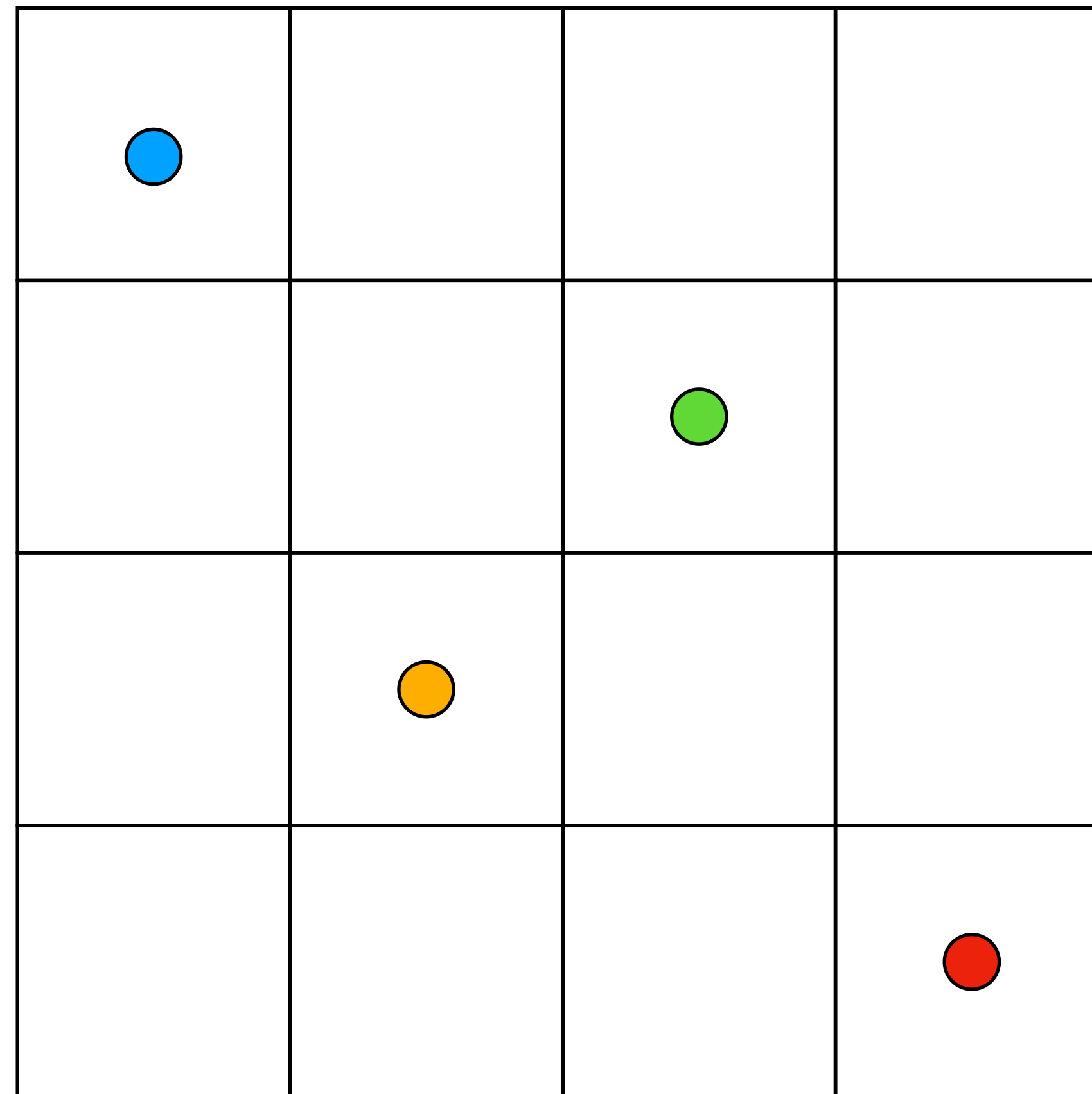
n -Rooks Sampling

Main Idea



n -Rooks Sampling

Main Idea



Russian Roulette

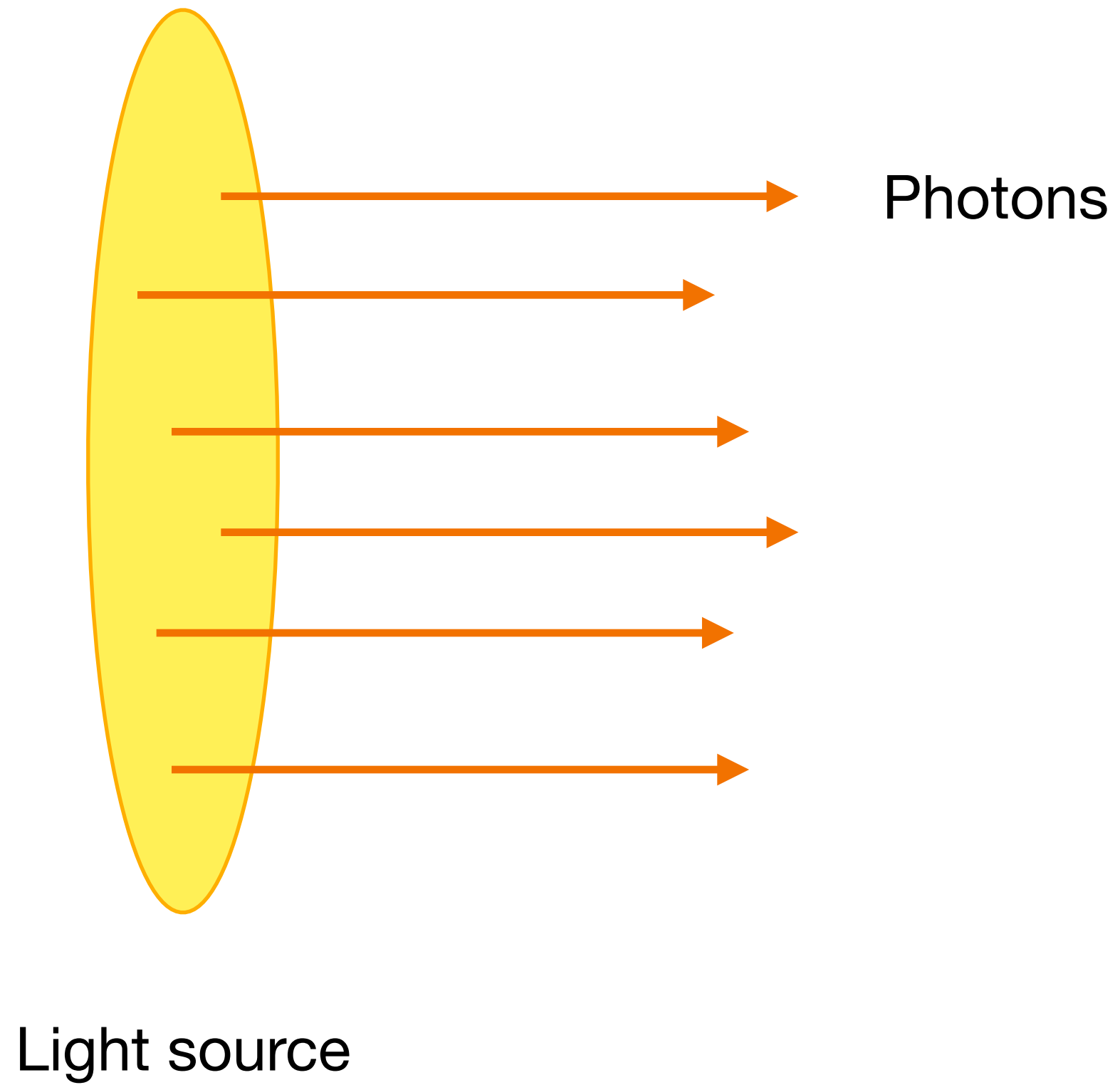
Russian Roulette

Main Idea

- Von Neumann and Ulam introduced this method that removes samples with low probability.
- Firstly, we need to split our domain into n sub-regions.
- For each sub-region, we need to know the probability, p_i , of that region to be picked.
- We generate a sample, \mathbf{x}_i , for that region with probability p_i .
- NOTE: This method can be used in both integration and simulations.

Russian Roulette

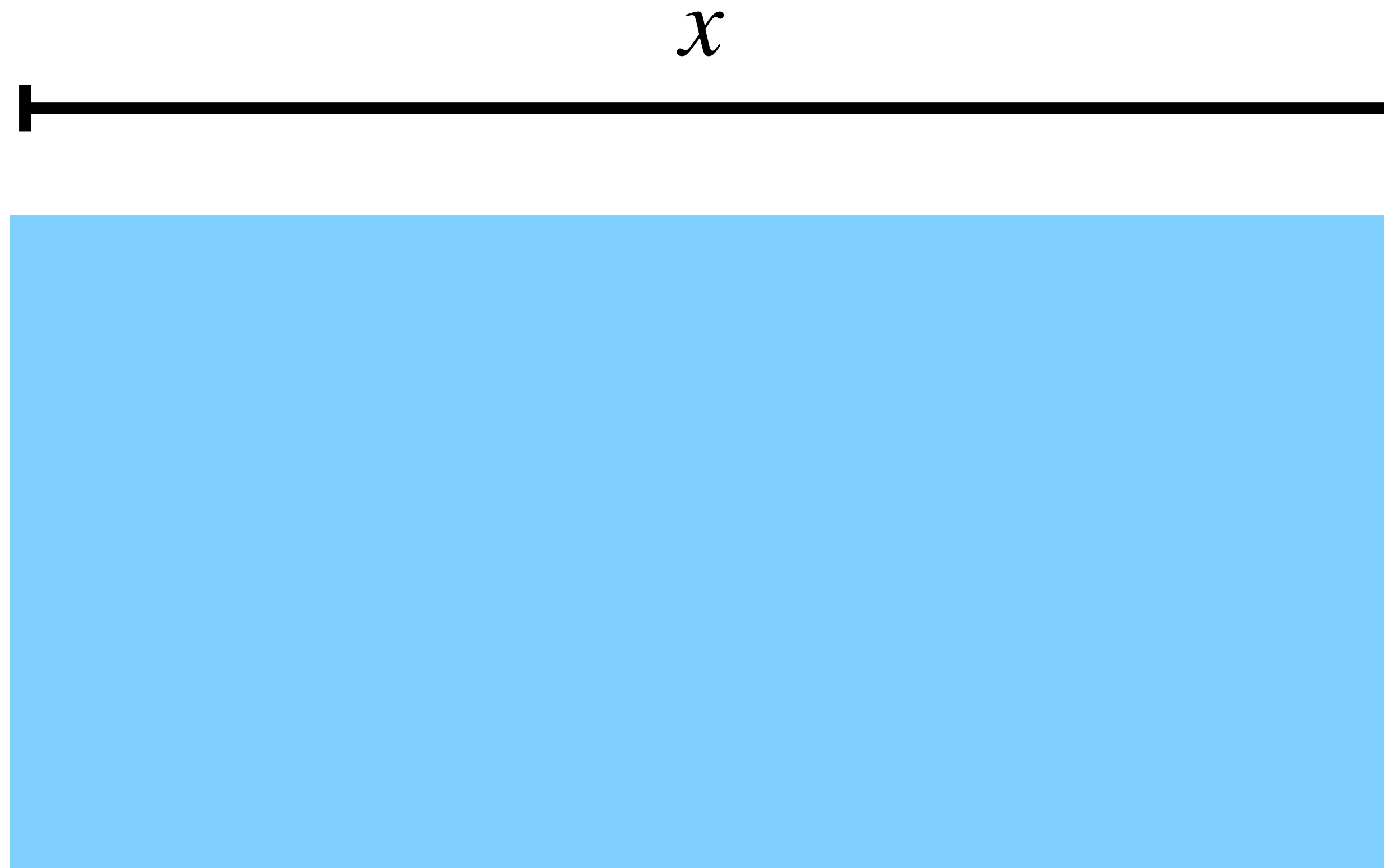
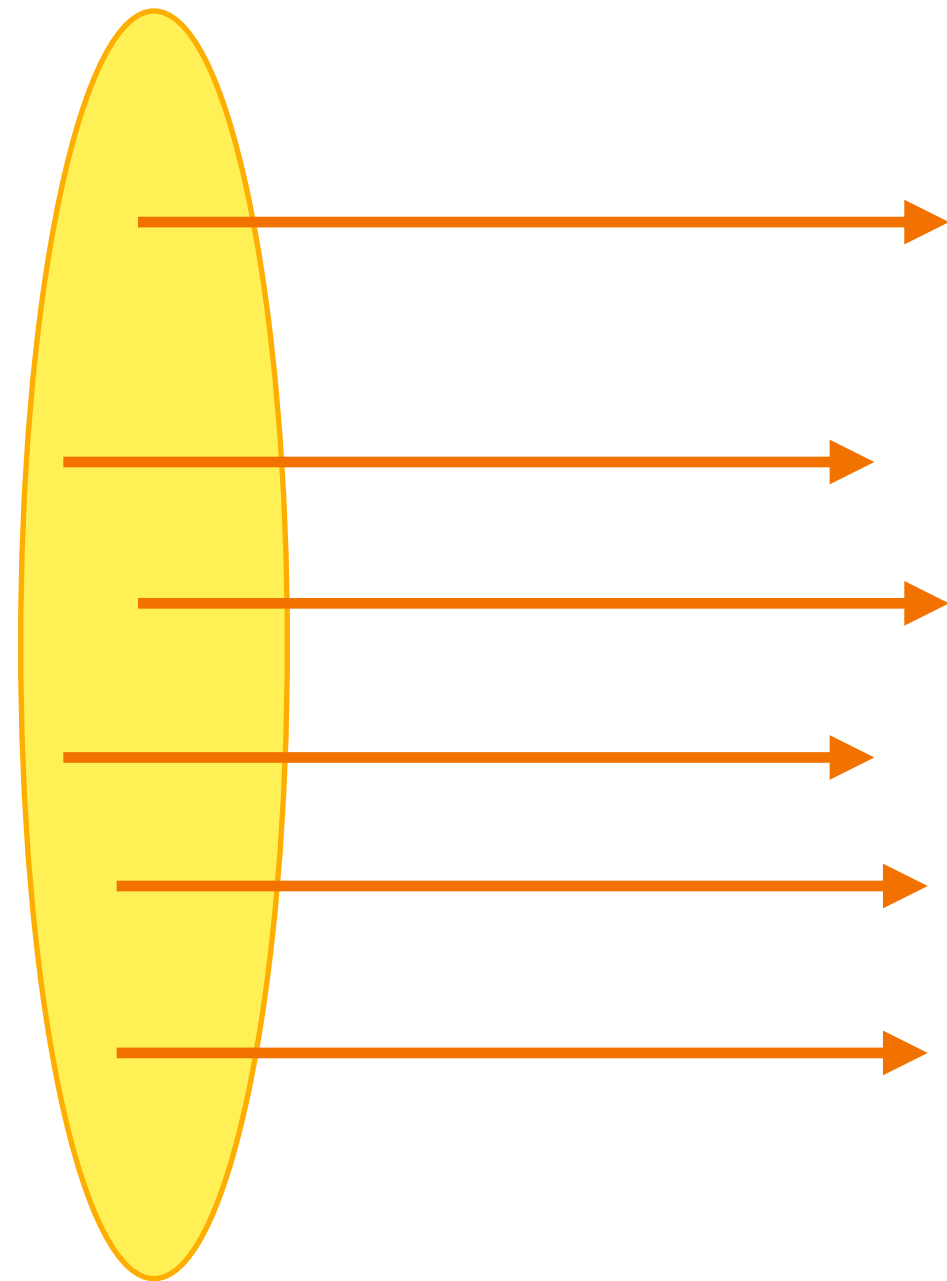
Example



We emit photons with power E .

Russian Roulette

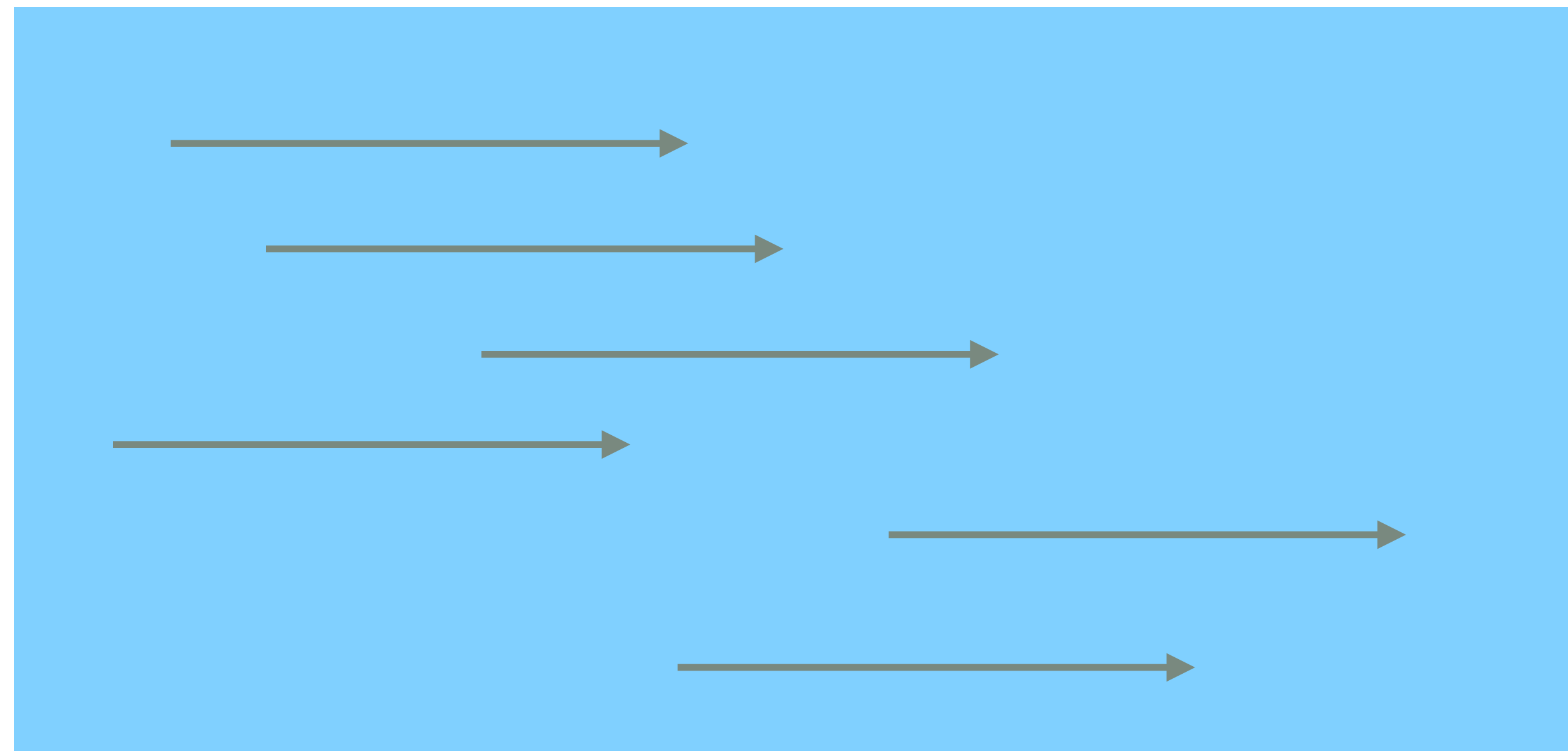
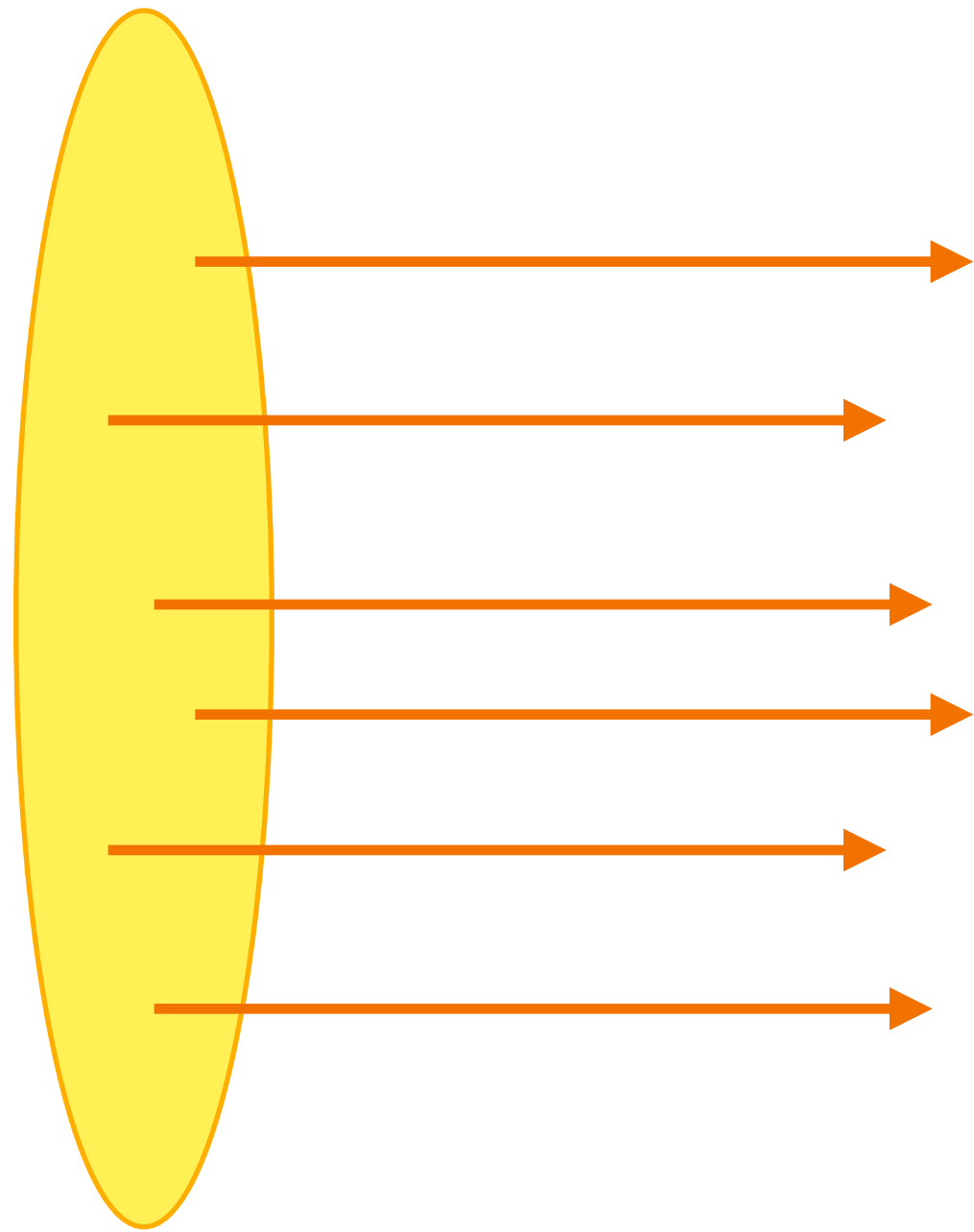
Example



We have a media that absorb the photon $\exp(-c_0x)$,
Beer's Law, where c is a constant of the media and x is
the travelled distance.

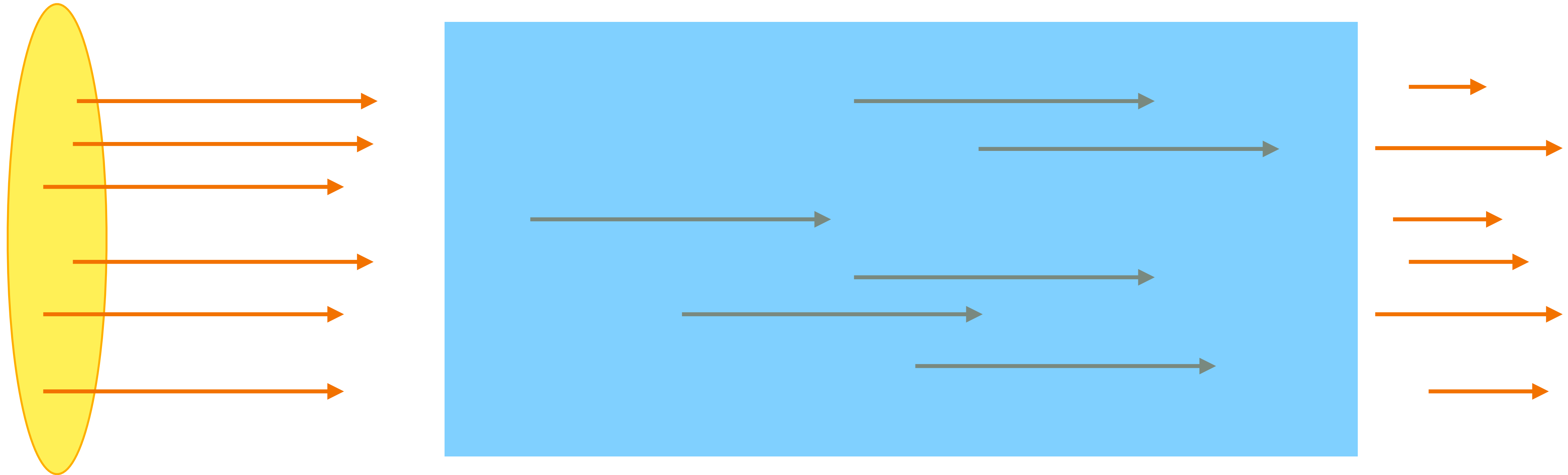
Russian Roulette

Example



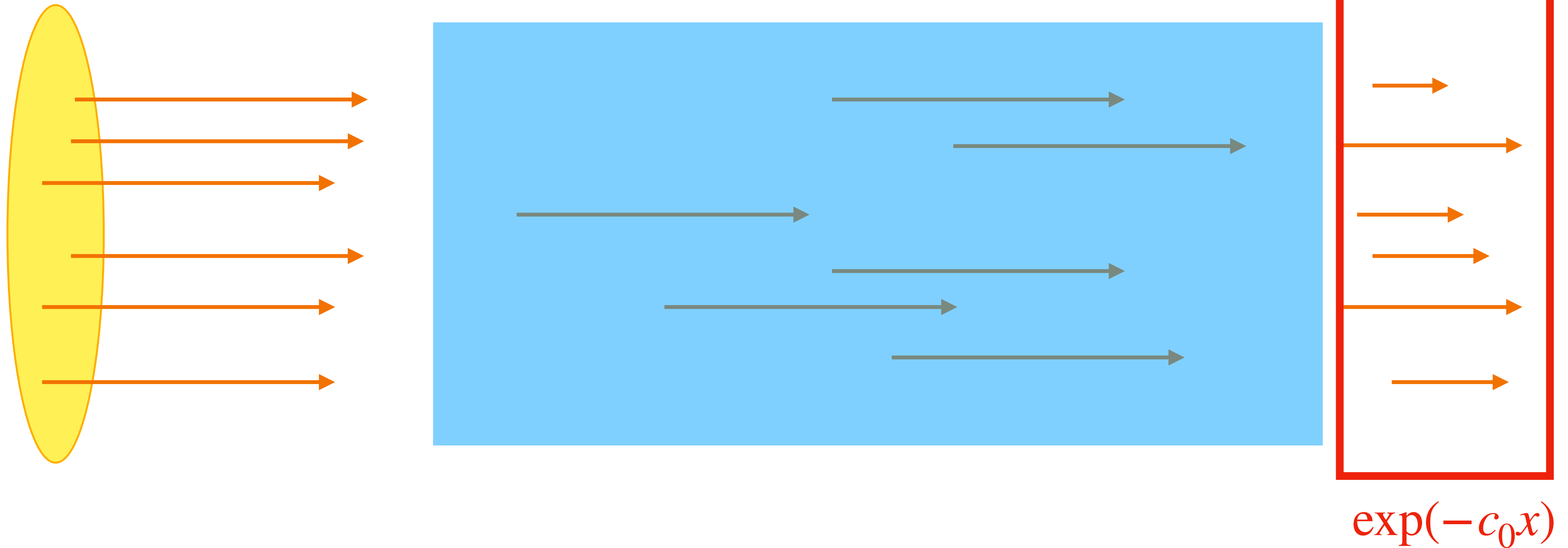
Russian Roulette

Example



Russian Roulette

Example



Russian Roulette

Example

- In this case, we want to estimate the mean energy reaching the end of the media, which absorbs photons' energy.
- If we reduce the power of each photon, we are left with low energy photons, so we start to have tiny values \rightarrow numerical issues with floating point numbers!
- We use Russian Roulette to avoid to sum tiny values up:
 - We keep photons with probability:

$$u < e^{-c_0 x} \quad u \in \mathbf{U}(0,1).$$

Importance Sampling

Importance Sampling

In Integration

- Importance sampling can be a powerful tool for reducing variance quickly.
- Let's recap how we estimate our averages:

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n g(\mathbf{x}_i) = \frac{1}{n} \sum_{i=1}^n \frac{f(\mathbf{x}_i)}{p(\mathbf{x}_i)} \quad \mathbf{x}_i \sim^{\text{i.i.d.}} p .$$

- How can we speed this up?
 - Drawing samples with a PDF that is close to our function f that we want to integrate.
 - We need to do this with care, it may backfire badly; e.g., infinite variance for a problem with finite variance!

Importance Sampling

Main Idea: The Ideal Distribution

- The ideal distribution for sampling would be

$$p(\mathbf{x}_i) \propto f(\mathbf{x}_i) \rightarrow p(\mathbf{x}_i) = cf(\mathbf{x}_i) .$$

- This means:

$$c = \frac{1}{\int_{\mathcal{D}} f(\mathbf{x}) d\mathbf{x}} .$$

- Note that this require to know the integral that we want to estimate!

Importance Sampling

Main Idea

- More in general, in our usual estimation:

$$\mathbb{E}(f(\mathbf{x})) = \int_{\mathcal{D}} f(\mathbf{x})p(\mathbf{x})d\mathbf{x} ,$$

we would like to speed estimation using $\mathbf{X} \sim q$, where q is a PDF. So, we have to:

$$\mathbb{E}(f(\mathbf{x})) = \int_{\mathcal{D}} f(\mathbf{x})p(\mathbf{x})d\mathbf{x} = \int_{\mathcal{D}} \frac{f(\mathbf{x})p(\mathbf{x})}{q(\mathbf{x})}q(\mathbf{x})d\mathbf{x} = \mathbb{E}\left(\frac{f(\mathbf{x})p(\mathbf{x})}{q(\mathbf{x})}\right) .$$

Importance Sampling

Main Idea

- This leads to the importance sampling estimator:

$$\hat{\mu}_{q,n} = \frac{1}{n} \sum_{i=1}^n \left(\frac{f(\mathbf{X}_i)p(\mathbf{X})_i}{q(\mathbf{X}_i)} \right) \quad \mathbf{X}_i \sim q .$$

- The important thing here is that we can compute the term:

$$\frac{f(\mathbf{X}_i)p(\mathbf{X})_i}{q(\mathbf{X}_i)} .$$

Importance Sampling

Main Idea

- When $q(\mathbf{X}_i) > 0$ and $f(\mathbf{X}_i)p(\mathbf{X})_i \neq 0$, we have that:

$$\mathbb{E}(\hat{\mu}_{q,n}) = \mu \quad \text{Var}(\hat{\mu}_{q,n}) = \sigma_q^2, \text{ where:}$$

$$\sigma_q^2 = \int_{\mathcal{Q}} \frac{(f(\mathbf{x})p(\mathbf{x}))^2}{q(\mathbf{x})} d\mathbf{x} - \mu^2 = \int_{\mathcal{Q}} \frac{(f(\mathbf{x})p(\mathbf{x}) - \mu q(\mathbf{x}))^2}{q(\mathbf{x})} d\mathbf{x} \quad \mathcal{Q} = \{\mathbf{x} \mid q(\mathbf{x}) > 0\}.$$

- **A good q helps us to reduce variance!**
- $(f(\mathbf{x})p(\mathbf{x}) - \mu q(\mathbf{x}))^2$ is small when $q(\mathbf{x}) \propto f(\mathbf{x})p(\mathbf{x})$.
- Small values of $q(\mathbf{x})$ destroys being proportional to $f(\mathbf{x})p(\mathbf{x})$.

Importance Sampling

Main Idea

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Importance Sampling

Main Idea

- When $q(\mathbf{X}_i) > 0$ and $f(\mathbf{X}_i)p(\mathbf{X})_i \neq 0$, we have that:

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- **A good q helps us to reduce variance!**
- $(f(\mathbf{x})p(\mathbf{x}) - \mu q(\mathbf{x}))^2$ is small when $q(\mathbf{x}) \propto f(\mathbf{x})p(\mathbf{x})$.
- Small values of $q(\mathbf{x})$ destroys being proportional to $f(\mathbf{x})p(\mathbf{x})$.

Importance Sampling

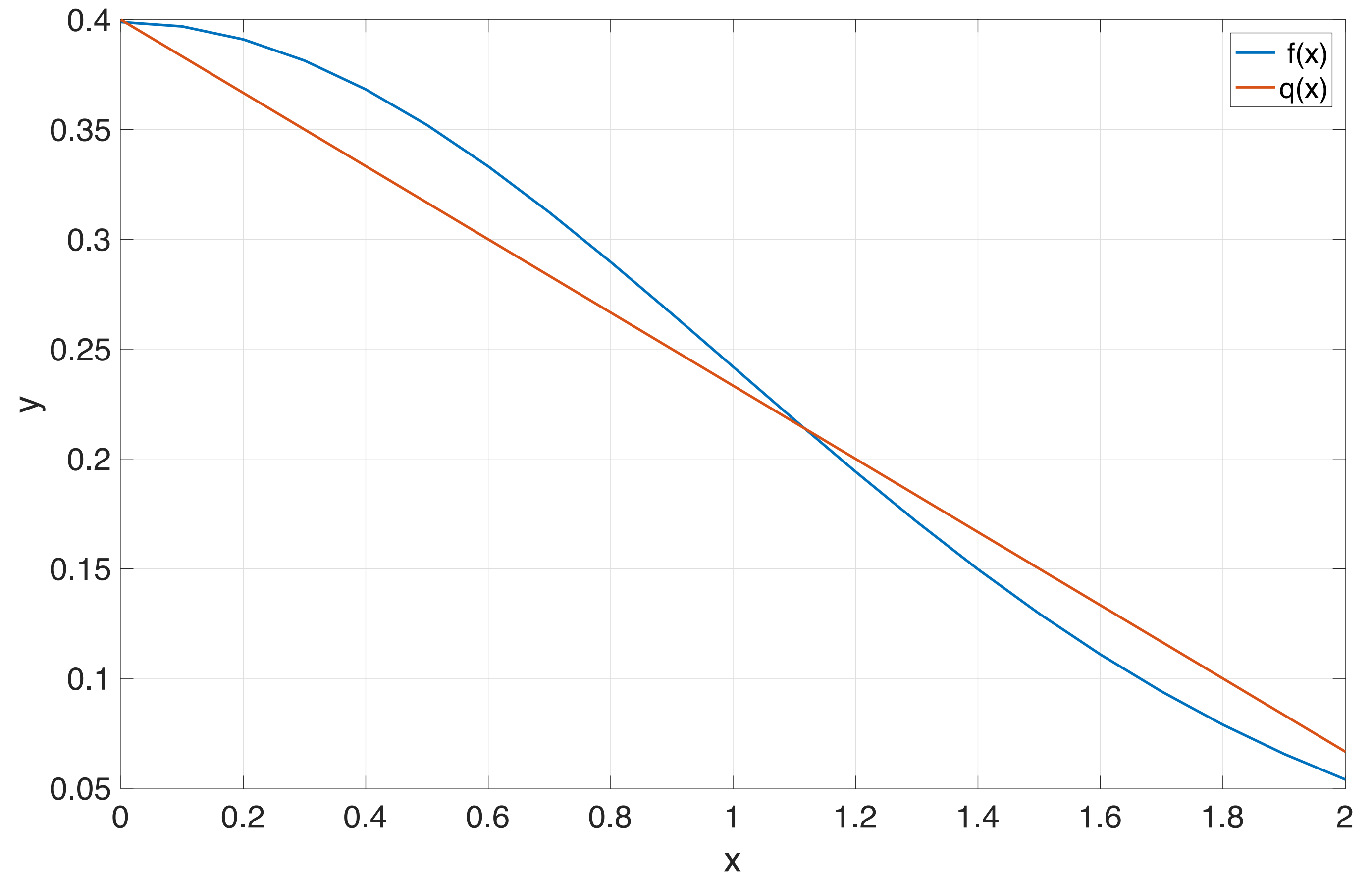
Main Idea

- Another insights is that a zero variance $q(\mathbf{x})$ means that we just need $f(\mathbf{x})$ and $p(\mathbf{x})$ to compute our estimate!
- How does this help us?
 - We should design $q(\mathbf{x})$ to follow energy peaks when $f(\mathbf{x})p(\mathbf{x})$ does!
 - To achieve this, we have to know the specific problem.

Importance Sampling

Example

- We want to integrate $N(0,1)$ in $[0,2]$.
- We use as guiding PDF:
$$q(x) = \frac{15}{7} \left(\frac{2}{5} - \frac{x}{6} \right).$$
- With 10,000 sample we get a $\sigma = 0.0445$, and this is less than $\sigma = 0.2291$ using uniform sampling.



Metropolis Sampling

Metropolis Sampling

Markov Chain

- A Markov Chain is a sequence of random variables, X_i .
- Such random variables have to satisfy the following:

$$P(X_{i+1} = x_{i+1} | X_i = x_i, \dots, X_1 = x_1) = P(X_{i+1} = x_{i+1} | X_i = x_i),$$

where $X_i \in \Omega$, the space state.

- This means that a Markov Chain does not have a memory; i.e., the next state depends only on the previous one.

Metropolis Sampling

Markov Chain

- When we have n states, we can define a $n \times n$ matrix called the transition matrix:

$$P = \begin{bmatrix} 0.0 & 0.5 & 0.25 & 0.25 \\ 0.1 & 0.05 & 0.8 & 0.05 \\ 0.9 & 0.05 & 0.0 & 0.5 \\ 0.2 & 0.35 & 0.45 & 0.0 \end{bmatrix}.$$

Note that $\forall_{i,j} P(i,j) \geq 0$ and $\sum_{j=1}^n P(i,j) = 1$.

Metropolis Sampling

Markov Chain

- A distribution, π , over Ω is stationary when:

$$\forall_{x \in \Omega} \pi(x) = \sum_{\Omega} \pi(y) P(y \rightarrow x), \text{ this means } \pi = \pi P,$$

where $P(x, y) = P(x \rightarrow y)$, $\sum_{\Omega} \pi(x) = 1$, and $\forall_{\mathbf{x}} \pi(\mathbf{x}) \geq 0$.

Metropolis Sampling

Main Idea

- Metropolis-Hastings Sampling draws samples by knowing only our PDF $p(\mathbf{x})$ or $\pi(\mathbf{x})$ in Markov Chain theory. Requirements:
 - $\pi(\mathbf{x})$ has to be positive;
 - We can evaluate $\pi(\mathbf{x})$.
- No need to:
 - Compute the CDF;
 - Invert the CDF.

Metropolis Sampling

Main Idea

- In MH, we accept/use a new generated sample \mathbf{x}_{i+1} as:

$$u \leq A(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1}) \quad u \in \mathbf{U}(0,1),$$

where:

$$A(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1}) = \min \left(1, \frac{\pi(\mathbf{x}_{i+1})T(\mathbf{x}_{i+1} \rightarrow \mathbf{x}_i)}{\pi(\mathbf{x}_i)T(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1})} \right).$$

Metropolis Sampling

Main Idea

- If the distribution is already at equilibrium we have detailed balance. This is defined as:

$$\pi(\mathbf{x}_{i+1})T(\mathbf{x}_{i+1} \rightarrow \mathbf{x}_i)A(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1}) = \pi(\mathbf{x}_i)T(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1}).$$

- Note that our problem is:

$$\mathbb{E}(f(\mathbf{x})) = \int_{\mathcal{D}} f(\mathbf{x})\pi(\mathbf{x})d\mathbf{x},$$

and our classic estimator is:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i) \quad \mathbf{x}_i \sim \pi.$$

Metropolis Sampling

Main Idea: Generating New Samples and the Transition Function

- How do we generate \mathbf{x}_{i+1} ?
 - We start from \mathbf{x}_i , and we modify/mutate it:
 - For this mutation, we have to know how to compute its PDF or:

$$T(\mathbf{x}_{i+1} \rightarrow \mathbf{x}_i) .$$

- Note that if $T(\mathbf{x}_{i+1} \rightarrow \mathbf{x}_i) = T(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1})$, we can simplify A as:

$$A(\mathbf{x}_i \rightarrow \mathbf{x}_{i+1}) = \min \left(1, \frac{\pi(\mathbf{x}_{i+1})}{\pi(\mathbf{x}_i)} \right) .$$

Metropolis Sampling

Main Idea: Mutations

- How do we mutate samples?
 - We should perturb samples with big changes rather than small ones:
 - We have to explore as fast as possible the entire domain to find peaks.
 - We do not want to explore a local minima:
 - Variance will increase as well if we do not move our samples around.
 - We also have to find a balance because too large mutations may be rejected more easily:
 - We can rely on more than one mutation strategy.

Metropolis Sampling

Main Idea: Start-up Bias

- How do we pick \mathbf{x}_0 ?
 - **Warm-up:** We may start with a random \mathbf{x}_0 , run some iterations of MH, and then we have to hope for the best. How many? $b = n/2$. So our estimator becomes:

$$\hat{\mu} = \frac{1}{n - b} \sum_{i=b+1}^n f(\mathbf{x}_i) \quad b < n.$$

- **Weighting:** We sample $\mathbf{x}_0 \sim p$, and then we need to take into account of this PDF by scaling the samples that we will draw by:

$$\frac{\pi(\mathbf{x}_0)}{p(\mathbf{x}_0)}.$$

Metropolis Sampling

Main Idea: Error

- To have an estimate of the error interval of our estimate, we use batching.
- We get n samples in total, which are the sum of l batches with k consecutive samples. We analyze our batches:

$$\forall_{j \in [1, l]} \quad \bar{y}_j = \frac{1}{k} \sum_{i=(j-1)k+1}^{jk} y_i \quad y_i = f(\mathbf{x}).$$

- So our error interval is given by

$$\bar{y} \pm t_{k-1}^{0.995} s \quad s^2 = \frac{1}{k(k-1)} \sum_{i=1}^k (\bar{y}_i - \bar{y})^2,$$

where t is the Student's t function

Some Extra Stuff

Common Random Numbers

Main Idea

- In some cases, we have to estimate:

$$\mathbb{E}(f(\mathbf{x}) - g(\mathbf{x})) = \mathbb{E}(f(\mathbf{x})) - \mathbb{E}(g(\mathbf{x})) \quad \mathbf{x} \sim p.$$

- Therefore, we can do our estimate in two ways:

$$\hat{\mu}_n^C = \frac{1}{n} \sum_{i=1}^n f(\mathbf{x}_i) - g(\mathbf{x}_i) \quad \hat{\mu}_n^I = \frac{1}{n_f} \sum_{i_f=1}^{n_f} f(\mathbf{x}_{i_f}) - \frac{1}{n_g} \sum_{i_g=1}^{n_g} g(\mathbf{x}_{i_g}).$$

- Note that the variance varies:

$$\text{Var}(\hat{\mu}_n^C) = \frac{1}{n} \left(\sigma_f^2 + \sigma_g^2 - 2\rho\sigma_f\sigma_g \right) \quad \rho \in [-1,1] \quad \text{Var}(\hat{\mu}_n^I) = \frac{1}{n} \left(\sigma_f^2 + \sigma_g^2 \right).$$

Moment Matching

Main Idea

- In some cases, we know $\mathbb{E}(\mathbf{X}) = \mu_{\mathbf{X}}$. When this happens, we can improve:

$$\hat{\mu}_n = \mathbb{E}(f(\mathbf{x})),$$

by adjusting samples mean as:

$$\hat{\mathbf{x}}_i = \mathbf{x}_i - \bar{\mathbf{X}} + \mu_{\mathbf{X}}.$$

- This can be extended to variance as well if we have it.

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Thank you for your attention!