Visual Appearance and Color

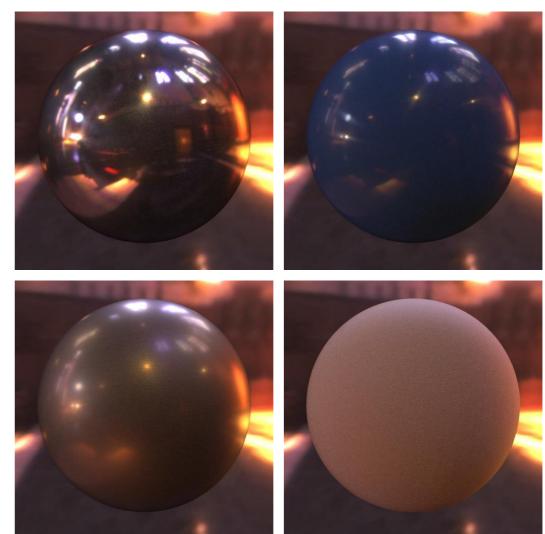
Gianpaolo Palma

Visual Appearance

 Color due to the interaction between the lighting environment (intensity, position, ...) and the properties of the object surface and material.



MATERIAL



Visual Appearance: why?

 Photorealistic rendering – High fidelity reproduction of the real world



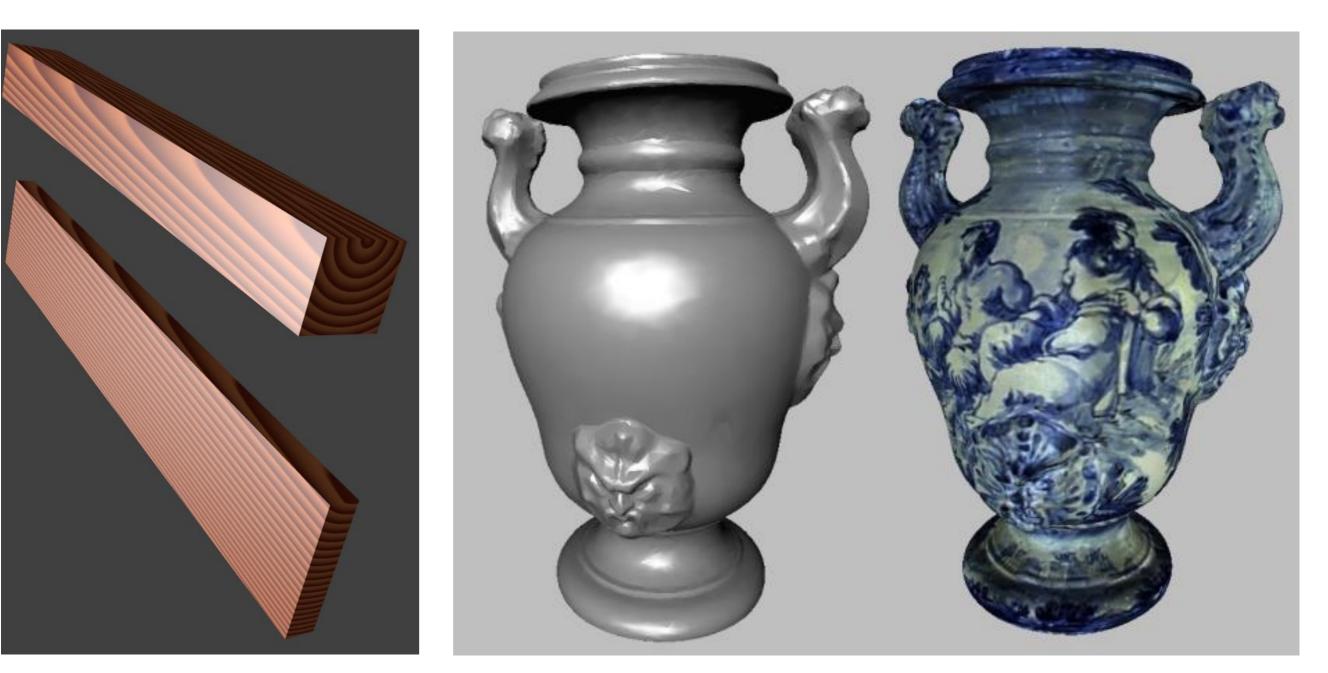
Visual Appearance: why?

 Perception – Better understanding of the details (even with a fake appearance)



Visual Appearance: why?

• To infer more cognitive data from color details



Physical-based Rendering

- Algorithms that compute images by simulating the physical behavior of light
 - Predictive simulation, photorealistic
 - But slow (simulation of physics is computationally very expensive)
 - Need accurate geometry, materials and lights

Model of light

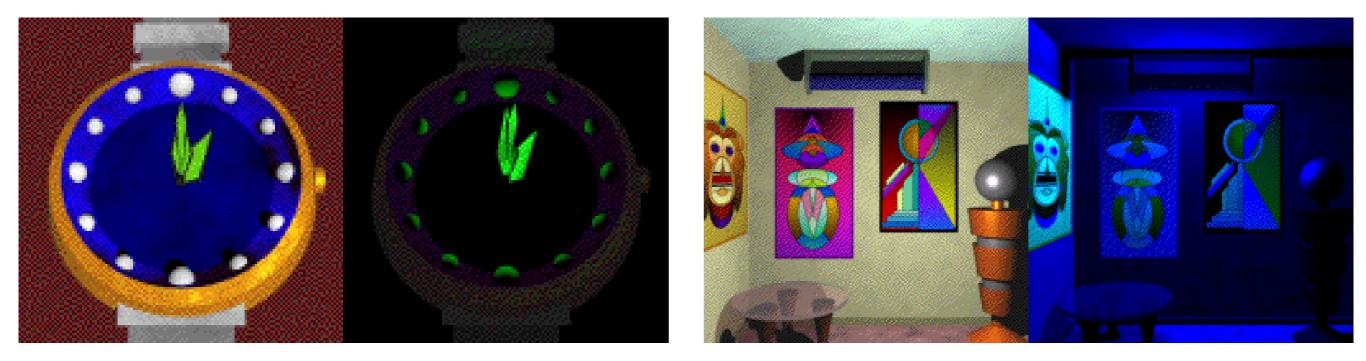
- Geometric optics
 - Light particles travel in straight lines
 - · Light particles do not interact with each other
 - Describes: emission, reflection/refraction, absorption





Model of light

- Quantum optics
 - Light particles are like any other quantum particles
 - Captures: fluorescence, phosphorescence



Model of light

- Wave optics
 - Light particles interact with each other
 - Describes: diffraction, interference, polarization



Rendering Equation

- Describe physical behavior of light in vacuum filled with objects
 - Based on geometric optics principles
 - Can be extended to describe participating media
 - Can be extended to describe wavelength and time dependency

Power and Irradiance

- Power: energy per unit time
 - Measured in Watts = Joules/sec

$$\Phi = \frac{dQ}{dt}$$

- Irradiance: power per unit area
 - Measured in Watts/meter²

$$E = \frac{d\Phi}{dA}$$

Radiance

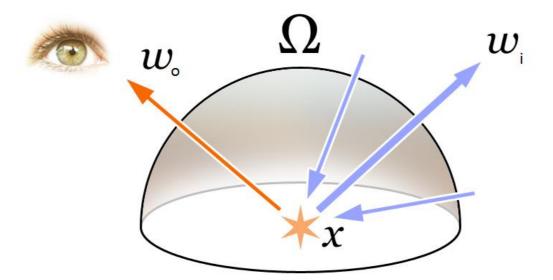
- Power per unit projected area and solid angle
 - Depends on position and direction

$$L(\mathbf{x} \to \Omega) = \frac{d^2 \Phi}{dA^{\perp} d\vec{\omega}_{\Omega}} = \frac{d^2 \Phi}{dA \cos \theta d\vec{\omega}_{\Omega}} = \frac{dE}{\cos \theta d\vec{\omega}_{\Omega}}$$

Rendering Equation

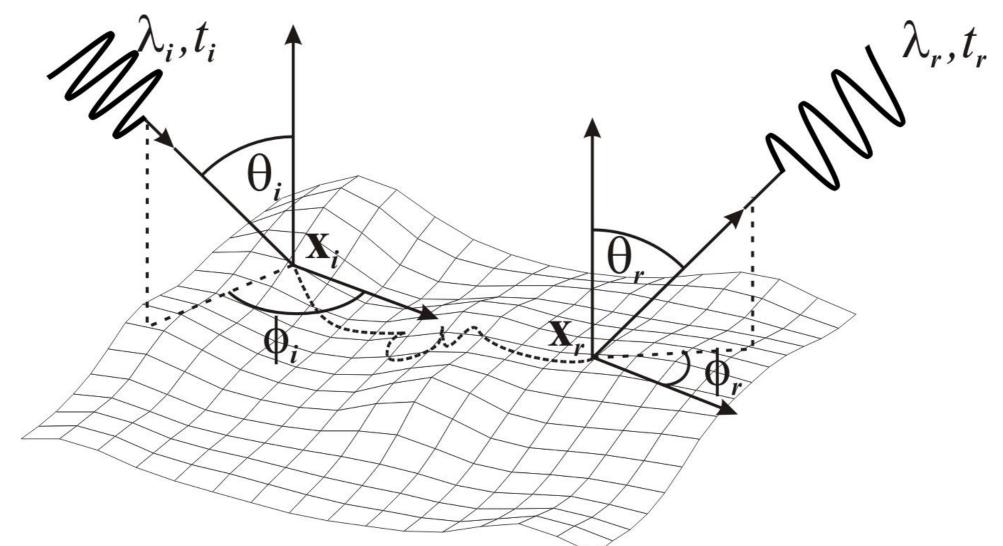
The outgoing radiance is the sum of emitted and reflected radiance

$$L(\mathbf{x} \to \vec{\omega}_o) = L_e(\mathbf{x} \to \vec{\omega}_o) + L_r(\mathbf{x} \to \vec{\omega}_o)$$
$$L_r(\mathbf{x} \to \vec{\omega}_o) = \int_{\vec{\omega}_i \in \Omega} L(\mathbf{x} \leftarrow \vec{\omega}_i) f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) (\vec{\omega}_i \vec{\mathbf{n}}) d\vec{\omega}_i$$

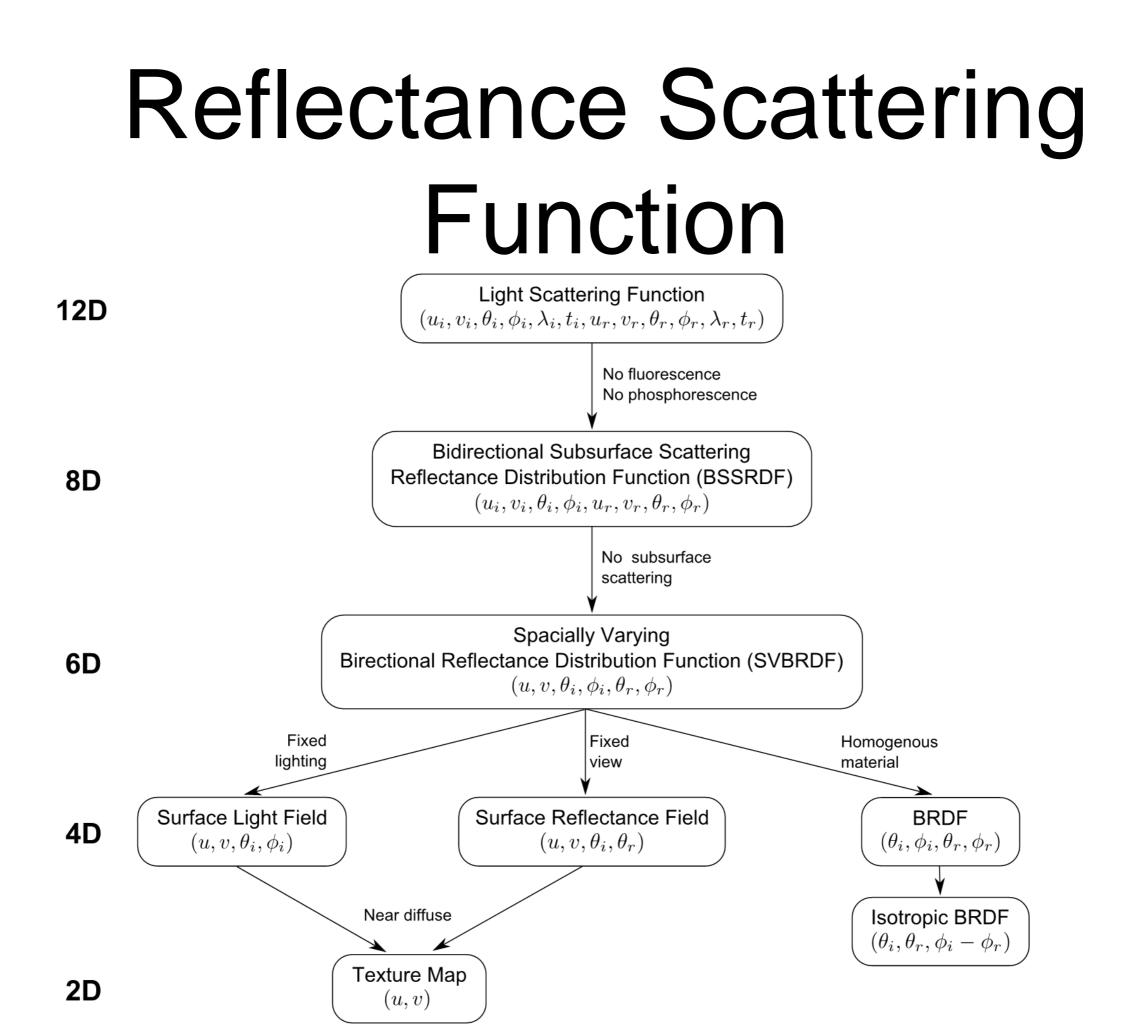


12D function

(Light and view direction, incident and outgoing surface point, wavelength, time)



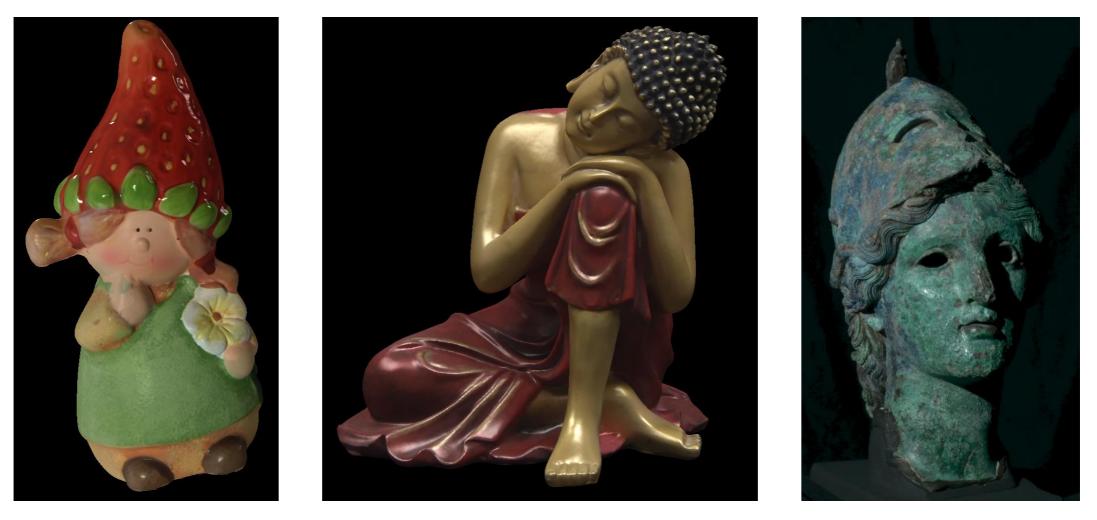
- No mathematical formulation
- Measurement impractical
- Simplification by constrains on the set of possible reflectance effects
 - Phosphorescence
 - Fluorescence
 - Subsurface scattering
 - Specular scattering
 - Backscattering
 - Diffuse scattering



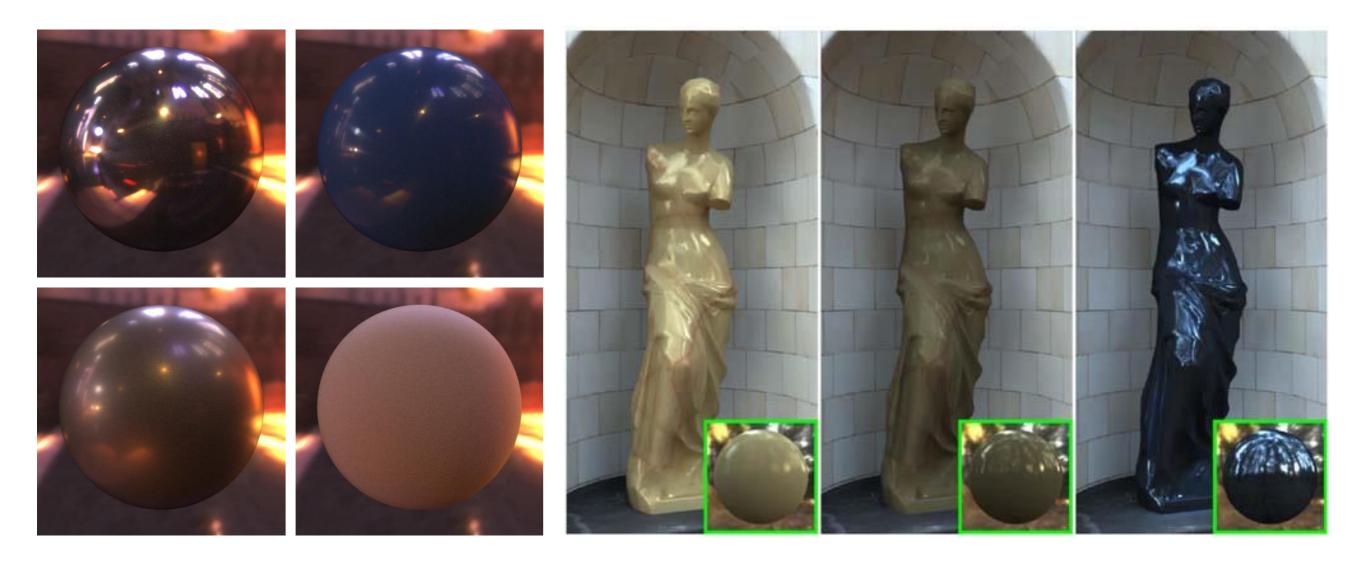
- BSSRDF (8D)
 - No fluorescence (no wavelength change)
 - No Phosphorescence (zero time light transport)
 - Subsurface scattering (translucent material)



- No Subsurface scattering (translucent material)
- Opaque material (reflection on the same place)
- Spatially varying glossy material



- BRDF (4D)
 - No spatially varying
 - Uniform material



- Light Field (4D)
 - Amount of light faring in every direction through every point in space (simplified plenoptic function)
 - Fixed lighting condition and variable view direction
 - Spatially varying
 - Image-based rendering (no geometry)
- Surface Reflectance Field (4D)
 - Fixed view position and variable light direction
 - Spatially varying
 - Image-based relighting (RTI)
 - Implicit geometry
 - No spatially varying
 - Uniform material

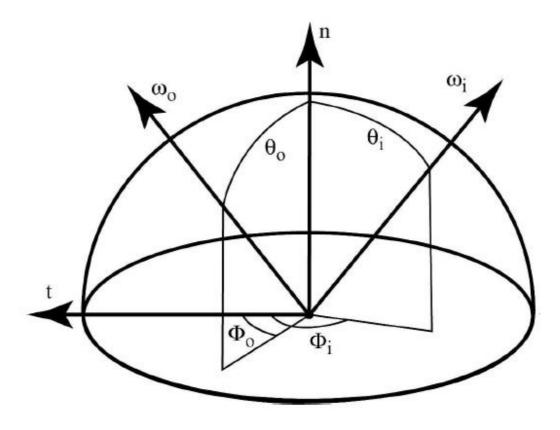
Visual Appearance: how to use?

- BSSRDF and BRDF
 - Model-based rendering
 - Explicit geometry
 - Modeling or acquisition of the appearance
 - Global illumination algorithm
 - More precise but computational heavy
- Light Field and Reflectance Field
 - Image based rendering
 - Set of photos ("interpolation")
 - No geometry or "implicit" geometry
 - Realistic rendering but trade-off between data and precision

BRDF

$$f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) = \frac{dL(\mathbf{x} \to \vec{\omega}_o)}{dE(\mathbf{x} \leftarrow \vec{\omega}_i)} = \frac{dL(\mathbf{x} \to \vec{\omega}_o)}{L(\mathbf{x} \leftarrow \vec{\omega}_i)\cos\theta d\vec{\omega}_i}$$

- Spatially varying (Heterogeneous materials)
- 6D Anisotropic



BRDF

- Properties
 - Energy conservation $\int_{\Omega} f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) \cos \theta d\vec{\omega}_i \leq 1$
 - Helmholtz reciprocity $f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) = f(\mathbf{x}, \vec{\omega}_o \to \vec{\omega}_i)$
- Simplification $f(u, v, \theta_i, \phi_i, \theta_o, \phi_o)$
 - Isotropic material 5D $f(u, v, \theta_i, \theta_o, \phi_i \phi_o)$
 - Homogeneous materials 4D $f(\theta_i, \phi_i, \theta_o, \phi_o)$
 - Homogeneous and isotropic $f(\theta_i, \theta_o, \phi_i \phi_o)$ material 3D

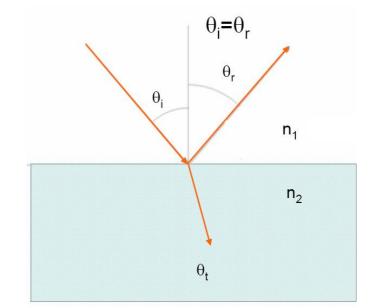
BRDF Models

- General model to approximate the form of the BRDF (diffuse and specular reflection, off-specular scattering, backscattering)
- Smooth surface
 - Maxwell's equation, Snell's law, Fresnel's equation
- Empirical Model
 - Function controlled by few parameters related to the observed effects
- Analytical Model
 - Physical principles applied to the surface microstructure (physical based rendering)

Smooth Surface

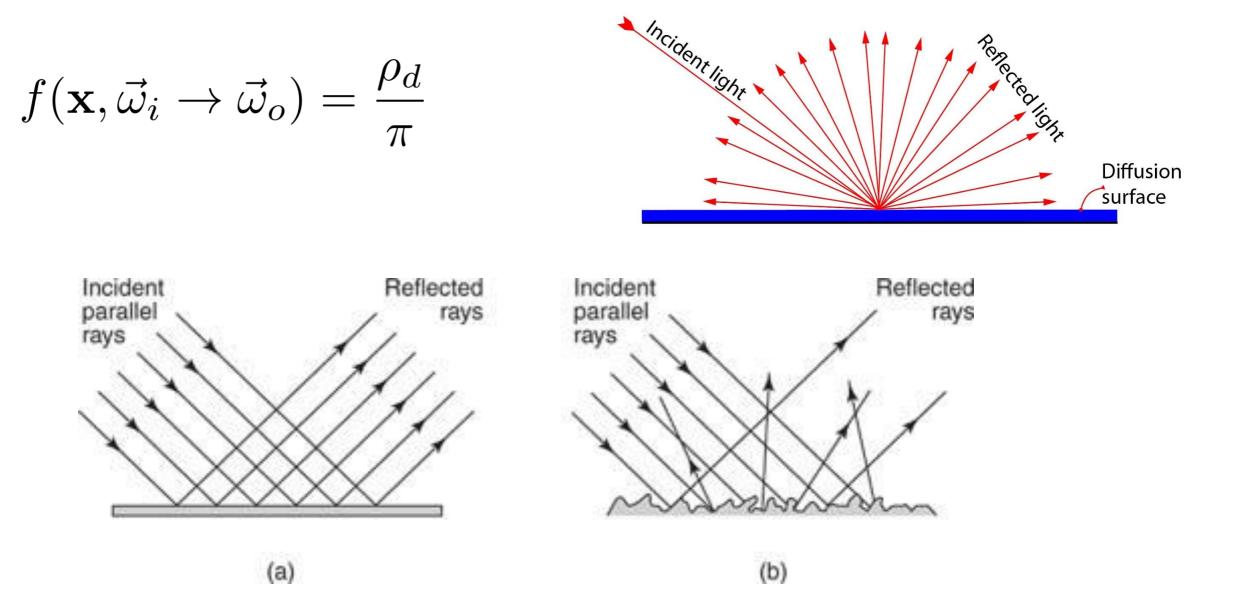
- Surface flat and infinite when viewed at the scale of wavelength of light (Rayleight criterion)
- Snell's law
 - Directionality of transmission and reflection
- Fresnel's equation
 - Fraction of light reflected
 - Schlick's approximation

$$F(\theta) = F(0) + (1 - \cos \theta)^5 (1 - F(0))$$



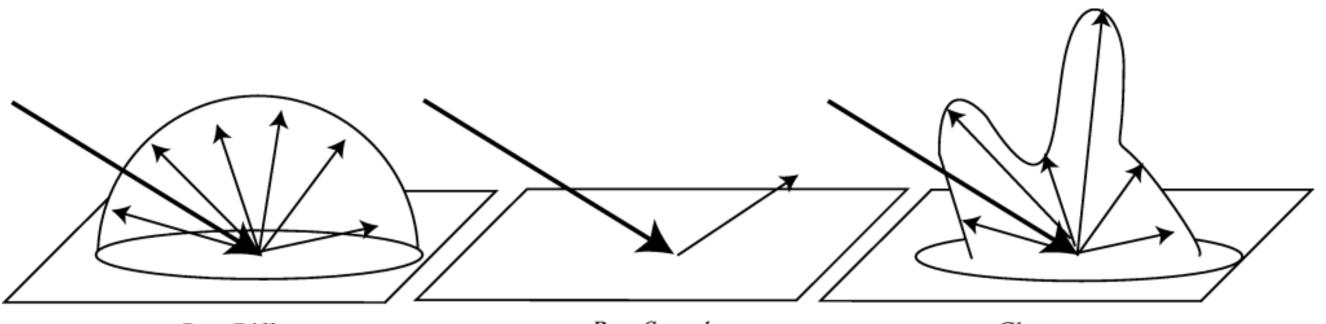
Lambertian BRDF

Light is reflected equally in all directions



Specular and Glossy BRDF

- Specular BRDF
 - Light is reflected only in one direction
- Glossy BRDF
 - Light is reflected in many directions unequally



Pure Diffuse

Pure Specular

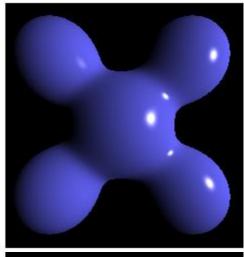
Phong and Blinn Models

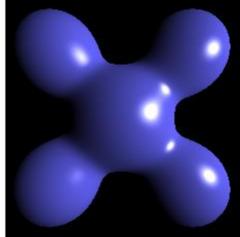
Phong

$$f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) = k_d + k_s (R \cdot \vec{\omega}_o)^n$$

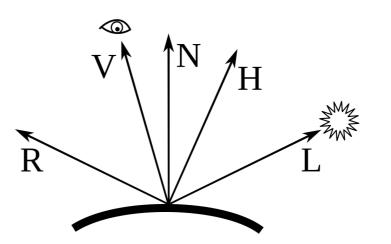
Blinn-Phong

$$f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) = k_d + k_s (N \cdot H)^n$$

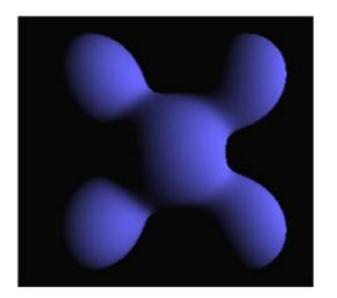




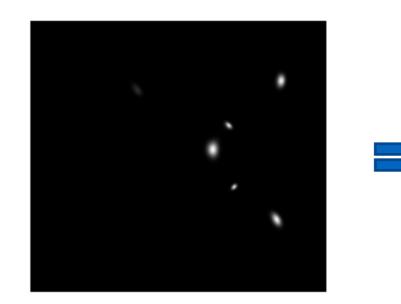
- Issues
 - Non reciprocal
 - Non energy conserving



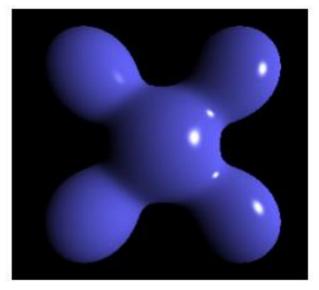
Phong Model



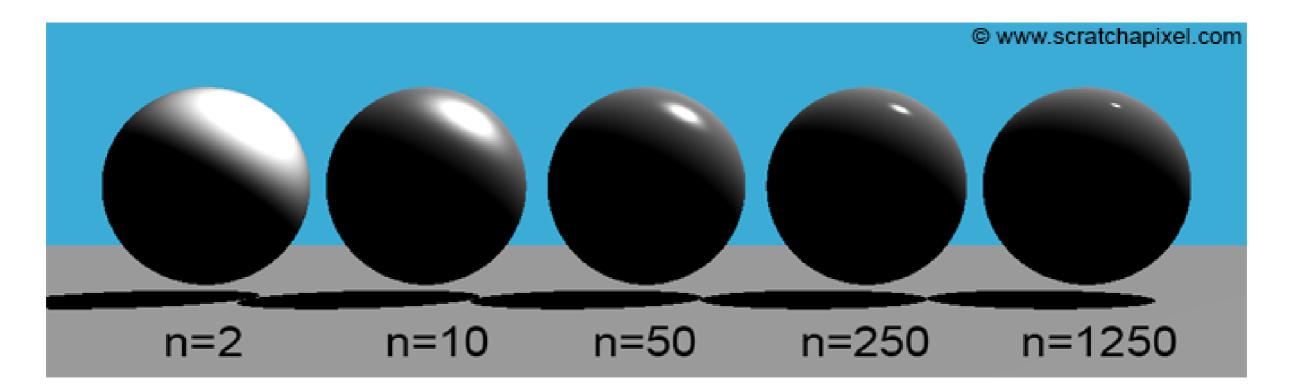
DIFFUSE



SPECULAR



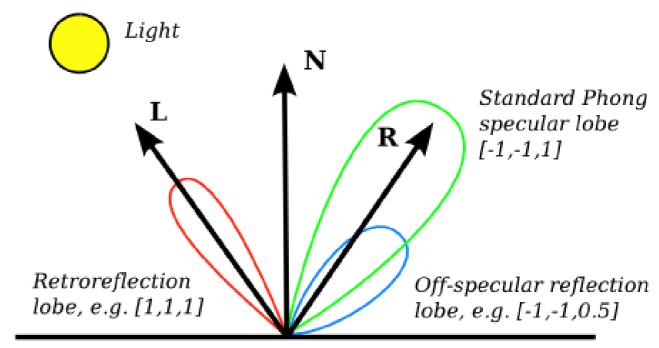
FINAL APPEARENCE



Lafortune Model

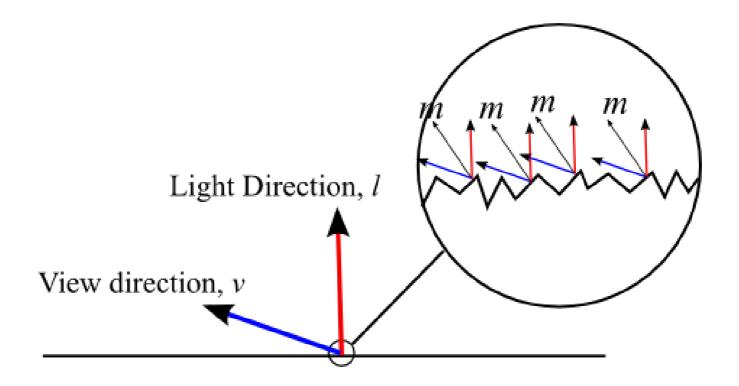
 $f(\mathbf{x}, \vec{\omega}_i \to \vec{\omega}_o) = f(\mathbf{x}, \vec{\mathbf{u}} \to \vec{\mathbf{v}}) = \rho_s (C_x u_x v_x + C_y u_y v_y + C_z u_z v_z)^n$

- Definition of lobes around any axes
- By appropriate normalization, a lobe conserves energy and obeys reciprocity
- Mechanism to model backscattering



Physical based model

- Microfacet theory
 - Surface is composed of many micro-facets and each micro-facet will only reflect light in a single direction according to their normal



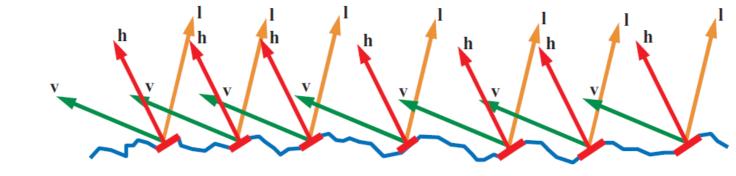
Physical based model

$$f(\vec{\mathbf{l}} \to \vec{\mathbf{v}}) = \frac{F(\vec{\mathbf{l}}, \vec{\mathbf{h}})G(\vec{\mathbf{l}}, \vec{\mathbf{v}}, \vec{\mathbf{h}})D(\vec{\mathbf{h}})}{4(\vec{\mathbf{n}} \cdot \vec{\mathbf{l}})(\vec{\mathbf{n}} \cdot \vec{\mathbf{v}})}$$

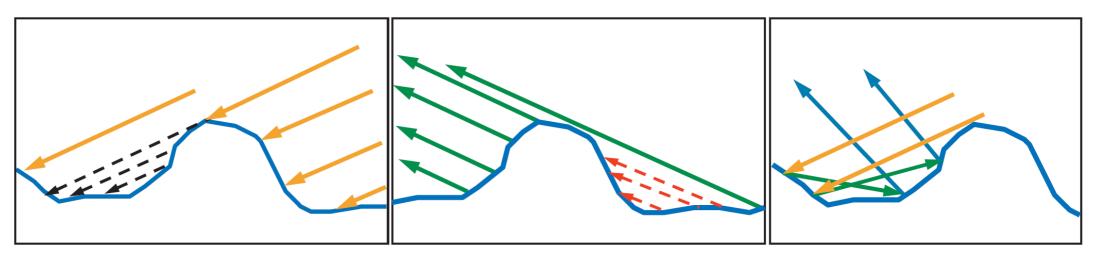
- Fresnel reflectance F
- Shadowing-masking function G
 - Percentage of the microfacets with normal equals to H are not shadowed or masked
- Microfacet normal distribution function D
 - Concentration of microfacets which are oriented thus that they could reflect light from I into v

Physical based model

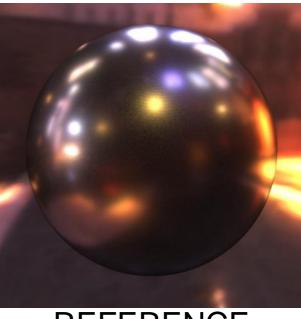
- The product of function D and G gives the concentration of active microfacets, that reflects light from I to v
- Shadowing-masking function G



Microfacet normal distribution function D



BRDF Models Comparison



REFERENCE

BLINN-PHONG



0.191

LAFORTUNE



0.123

COOK-TORRANCE



BRDF Measurement

- Acquiring outgoing radiance for each point from different view direction and by lighting the point from different light direction
 - Store the data in tabular form
 - Non-linear minimization to fit a parametric models to the acquire data

Gonioreflectometer

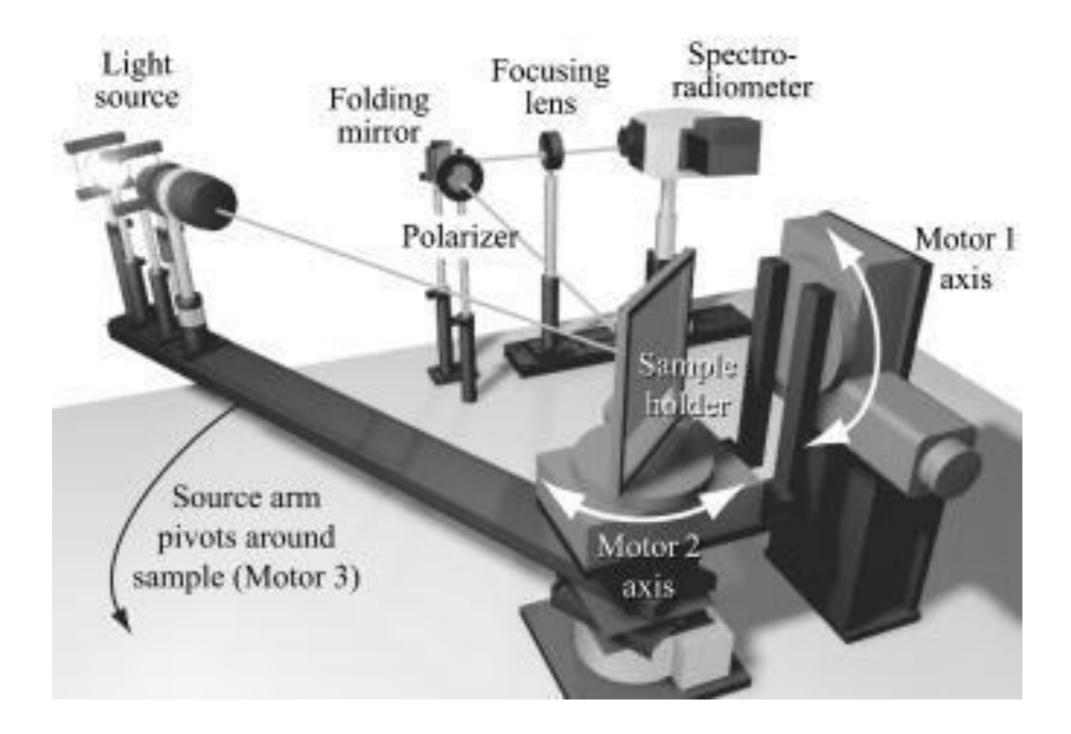


Image-based measurements

[Lensch et al., TOG 03]

- Image-based acquisition in a dark room with a single light
- Automatic identification of the main materials



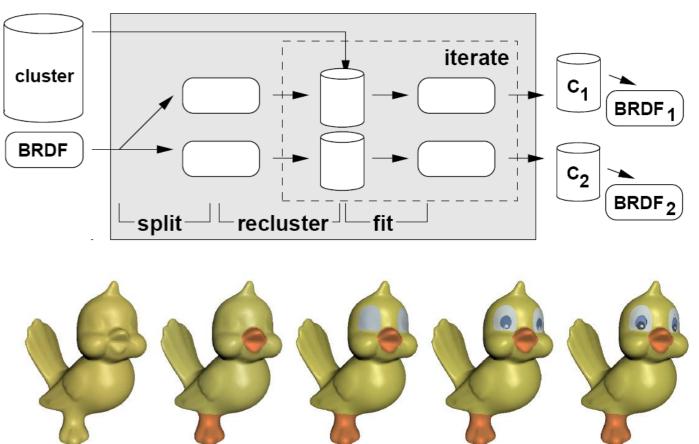


Image-based measurements

- Acquisition of complex scene under natural illumination condition
- BDRF measurement of a set of representative samples.
- Assign the BRDF using a small set of photo under natural illumination



[Debevec et al., 2004]







Perceived Color

- The simplest approximation of the appearance is just a simple color for point
- Even if some 3D scanner return color information, this data has low quality
- Solution: ad-hoc photographic campaign and projection on the 3D geometry









Perceived Color Reprojection

- Inverse projection, transferring the color from the images to the 3D surface
- Issues
 - Align each photo to the 3D models (camera calibration)
 - How to reproject the color on the 3D surface
 - How to select the most correct color

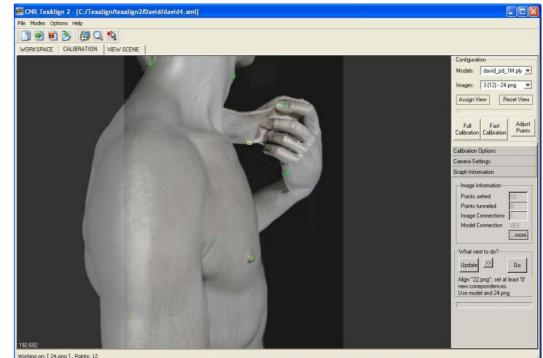
- Estimate for each photo the pin-hole camera model parameters (intrinsic and extrinsic parameters w.r.t. the reference system of the 3D models)
 - Manual method Selection of 2D-3D (x, X) correspondences and non-linear minimization algorithm

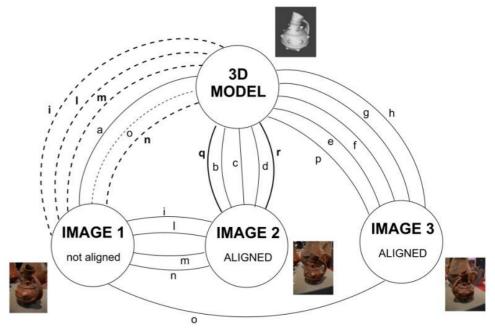
$$\min_{P} \|PX - x\|^2$$

Automatic method

[Franken et al., 2005]

- Select pairs of correspondences (2D-to-3D, 2D-to-2D) to compute the camera parameters
- Graph of correspondences to infer new 2D-to-3D pairs and to help the user to complete the registration
- Manual selection (possible inaccuracies, time-consuming)

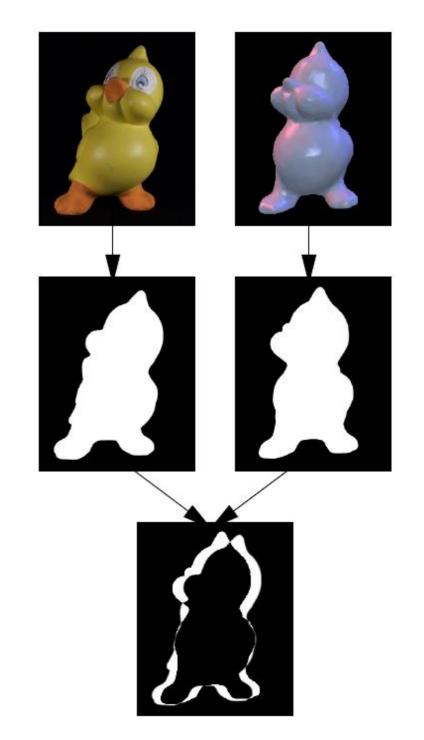




TOTAL COST: 3

[Lensch et al., GM 01]

- Compute the silhouette on image
- Render the 3D model and compute the silhouette
- Compute the pixels covered by just one silhouette
- Greedy iteration, by small rotation, until silhouette matching error is below a threshold
- Limitation
 - Silhouette extraction
 - All object visible in each image



Mutual Information

The amount of information about a random variable B that a random variable A contains

$$M(I_A, I_B) = \sum_{(a,b)} p(a,b) \log\left(\frac{p(a,b)}{p(a)p(b)}\right)$$

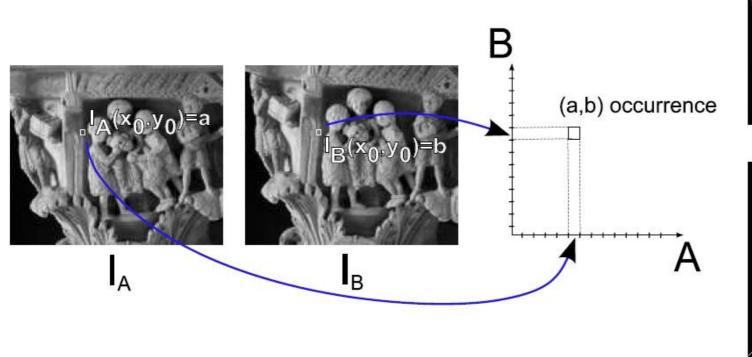
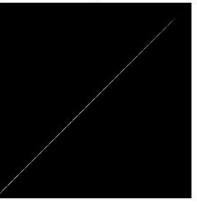


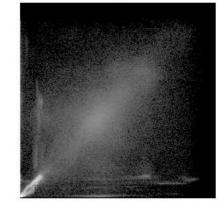


Image A



 $\mathcal{H}(A,A)$

Image B



 $\mathcal{H}(A,B)$

[Corsini et al., PG 09]

- Correlate the shading variations on the image with a particular rendering of the 3D model using the Mutual Information
 - Normal map
 - Ambient occlusion
 - Reflection map
 - Combined version



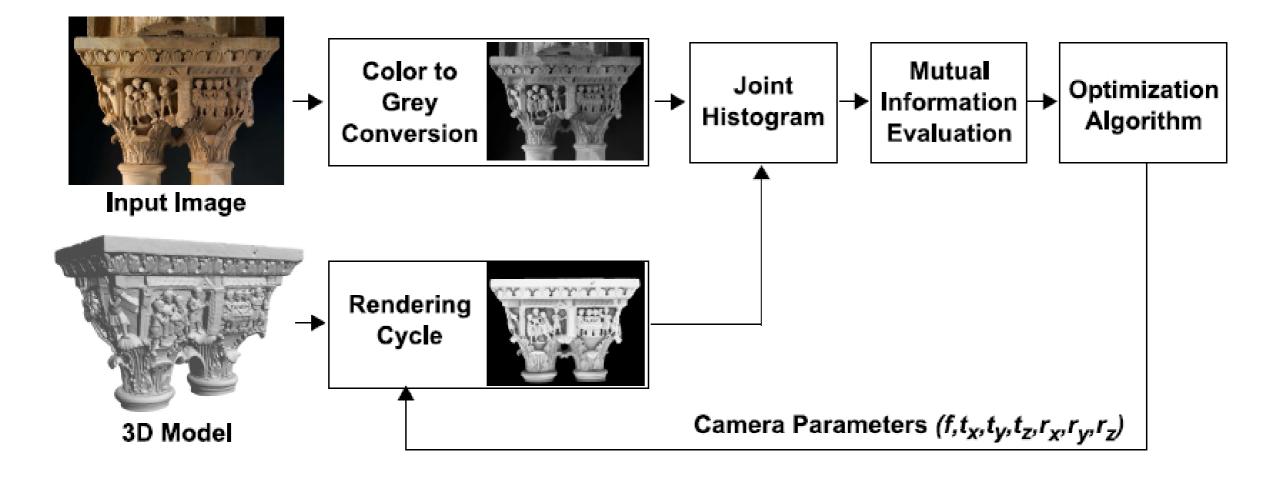






[Corsini et al., PG 09]

Algorithm overview



Encoding of the Color

- Texture
 - Compute a texture parametrization

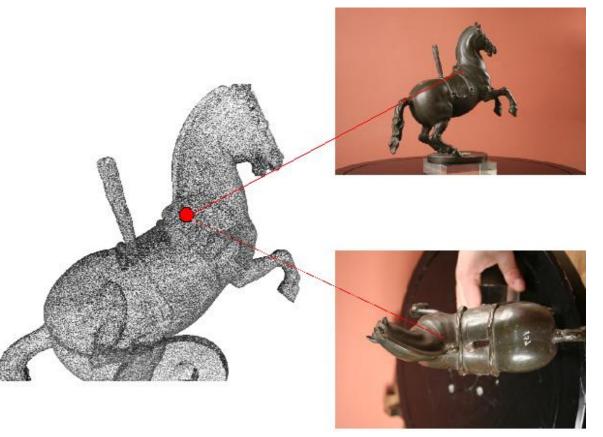


- Per-vertex color
 - Store the color for each vertex
 - Inside the triangle the color is obtained with barycentric interpolation

Color Integration

- How to select the most correct color
 - Select the right color among different images
 - Dealing with discontinuities between images that cover adjacent area
 - Reducing the illuminationrelated artifact (shadows, highlight)





Automatic Texture Mapping

[Callieri et al., VMV 03]

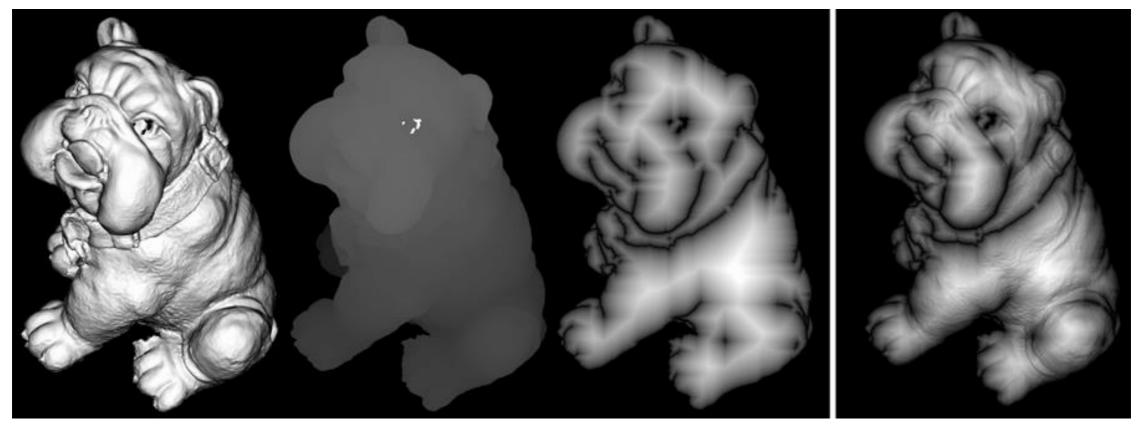
- For each area, the better (orthogonal) photo is chosen
- Mesh is split according to the photo allocation and parametrized using perspective projection
- From photos, the used area is cut and packed in the texture
- Color discordances on borders are corrected



Color Blending

[Callieri et al., C&G 08]

- Classify the quality of each pixel to compute the weighting blending
- Compute multiple masks for each images (View angle, depth, distance from border, stencil, focus, etc.)
- Compose the mask and use result as per-pixel weighting factor



References

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